

Growth law

$$f_{\text{uk}} = \kappa^e \cdot \frac{\partial E}{\partial E^e} + m^e e_k I + \tilde{B}_{\text{uk}}^{(g)} \quad \begin{matrix} \text{free energy per} \\ \text{unit mass?} \end{matrix}$$

κ : refers to the growth stage (intermediate), before the elastic deformation.

For small strains we have

$$\tilde{\epsilon} = \tilde{\epsilon}_k^e + \tilde{\epsilon}_k^o \quad g: \text{growth}$$

Additive partition of strains. A result of the multiplicative partition of the deformation gradient tensor $\tilde{F} = \tilde{F}^e \cdot \tilde{F}^o$

A type of E (free energy) for growth

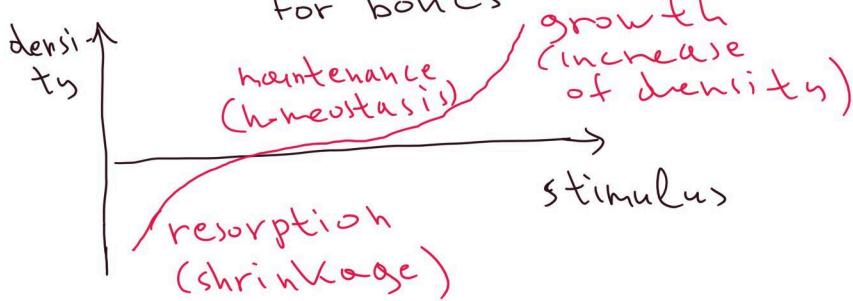
$$E(E_G, m) = m e(E_G, m) = \left(\frac{m}{m_h} \right)^{n_1} f(E_G)$$

free energy per unit volume

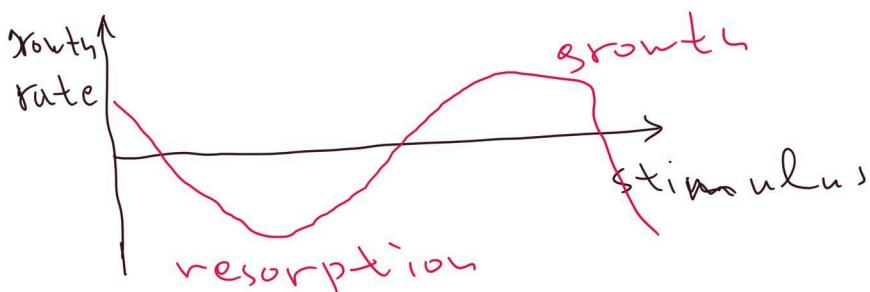
m : current mass

m_h : homeostatic mass

For bones



For soft tissues



Features of growth

- 1) May involve growth strain or not.
- 2) Material elastic or viscoelastic
- 3) Single phase or mixture
- 4) Exchange of mass only or energy as well with the surrounding
- 5) Growth only or restructuring as well. (remodelling)

Example of constitutive law for ~~an~~ an elastically growing material

$$\underline{\sigma} = m \underline{\underline{E}}(m) : \underline{\underline{E}}_G$$

↗ 4th order stiffness tensor ↘ 2nd order tensor of strain

accompanied by the mass exchange equation

$$\frac{dm}{dt} = a(m) + \underline{A}(m) : \underline{\underline{E}}_G + \underline{\underline{E}}_G : \underline{\underline{C}}(m) : \underline{\underline{E}}_G$$

$a(m)$: scalar function of mass

$\underline{A}(m)$: tensor (2nd order) function of mass

$\underline{\underline{C}}(m)$: 4th order tensor of mass

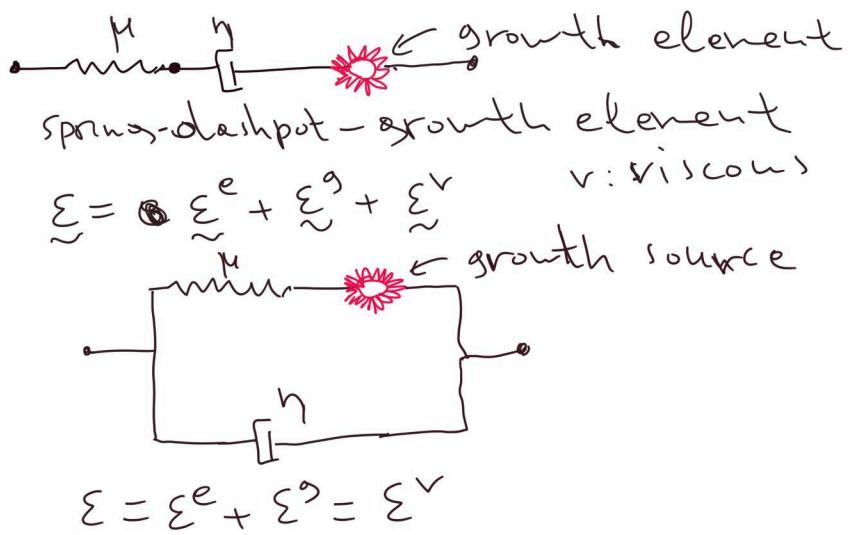
Growth models with growth strain

A viscoelastic model of a Maxwell isotropic, incompressible fluid

$$\underline{\sigma} = -P \underline{\underline{I}} + \underline{\underline{\xi}}, \quad \underline{\underline{\xi}} + t_r \frac{d\underline{\underline{\xi}}}{dt} = 2\mu t_r \left(\frac{d\underline{\epsilon}}{dt} - \frac{d\underline{\epsilon}^e}{dt} \right)$$

↓ deviator of stress Constitutive equation
 Deviatoric rhs,
 $\underline{\underline{\xi}} - \underline{\underline{\epsilon}}^e = \underline{\underline{\xi}}^e$

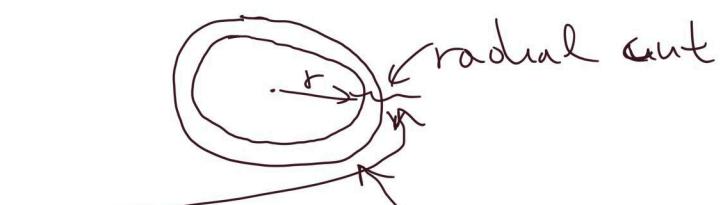
Viscoelastic models involving growth



Example of constitutive equation for
 $\dot{\varepsilon}^g$ $\frac{d\dot{\varepsilon}^g}{dt} = \frac{\alpha_g}{t_g} : (\sigma + \beta)$ t_g , α_g \leftarrow tensor growth
 characteristic parameter
 time related to growth

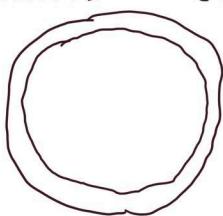
Growth, accommodation, residual stress

Application to a circular, cylindrical artery wall



Stresses exist, prior to application of loads, that keep the two tips of the cut glued together.

Reference configuration



$$\tilde{\sigma} = 0,$$

$$\tilde{F} = \tilde{F}^e = \tilde{f}^g = \tilde{I}$$

$$B(r, \theta, z)$$

$\xrightarrow{F^g}$
grow
(no stresses applied)

Gross of intermediate configuration

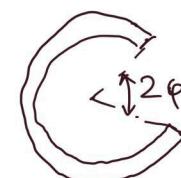


$$\tilde{\sigma} = 0$$

$$\tilde{F} = \tilde{F}^g$$

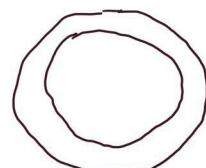
$$\tilde{F}^e = \tilde{I}$$

$$B_e(r_e, \theta_e, z_e)$$



The angular displacement of the tips of the cut, indicate the presence of residual stresses in the intact artery

Current configuration



$$\xrightarrow{F^e = F^a}$$

α : assemble
(glue again
the tips of
the cut to-
gether)

$$\tilde{\sigma} \neq 0$$

$$\tilde{F} = \tilde{F}_n^e \cdot \tilde{f}_n^g$$

$$\tilde{F}^e \neq \tilde{I}$$

$$B(r, \theta, z)$$

The total deformation gradient tensor

$$\tilde{F} = \text{diag} \left[\lambda_r = \frac{\partial r}{\partial \underline{r}}, \lambda_\theta = \frac{r}{\underline{r}}, \lambda_z \right]$$

$$\underline{r} = r(\underline{r}, t)$$

The intermediate components of generalized displacements, are

$$r_e = \underline{r}, \quad \theta_e = \theta \frac{\phi_e}{\pi}, \quad z_e = \lambda_z z$$

Then

$$\tilde{F}^g = \text{diag} \left[\lambda_{gr} = 1, \lambda_{g\theta} = \frac{\phi_e}{\pi}, \lambda_{gz} \right]$$

From the 2nd to the 3rd configuration

$$r = r(r_e), \theta = \theta e^{\frac{\pi}{\varphi_0}}, z = \lambda_{e2} z_e$$

$$\tilde{F}^e = \text{diag} \left[\lambda_{er} = \frac{dr}{dr_e}, \lambda_{e\theta} = \frac{r}{r_e} \frac{\pi}{\varphi_0}, \lambda_{ez} \right]$$

$$\tilde{E}_G^e = \frac{1}{2} \left[(\tilde{F}^e)^T \cdot \tilde{F}^e - I \right] = \frac{1}{2} \text{diag} \left[\lambda_{er}^2 - 1, \lambda_{e\theta}^2 - 1, \lambda_{ez}^2 - 1 \right]$$

For incompressible material, $\det F^e = 1$, so the mapping between the from the 2nd to the 3rd configuration, in terms of radius, is given by

$$r^2 - r_1^2 = (r_e^2 - r_{e1}^2) \frac{\varphi_0}{\pi} \frac{1}{\lambda_{ez}} = (r_e^2 - r_1^2) \frac{\varphi_0}{\pi} \frac{1}{\lambda_{ez}}$$

r_1 : inner ~~or~~ final radius

r : radius of any point in the well in the final configuration

We have a single equilibrium equation (the others are satisfied identically)

$$\frac{\partial \sigma_r}{\partial r} + \frac{1}{r} (\sigma_r - \sigma_0) = 0 \quad (1)$$

The stress-strain relations are (for incompressible material)

$$\tilde{\sigma} + P \tilde{I} = \text{diag} \left[\frac{\partial E_k}{\partial E_{er}} \lambda_{er}^2, \frac{\partial E_k}{\partial E_{G\theta}} \lambda_{e\theta}^2, \frac{\partial E_k}{\partial E_{Gz}} \lambda_{ez}^2 \right] \quad (2)$$

<sup>u: for intermediate
configuration</sup>

Then the equilibrium equation (1), from constitutive equations (2), yields after integration

$$\sigma_r(r) - \sigma_r(r_1) = \frac{\pi}{\varphi_0} \frac{1}{\lambda_{ez}} \int_{r_{e1}}^{r_e} (\sigma_r - \sigma_0) \frac{1}{\lambda_{e\theta}^2} \frac{dr_e}{r_e}$$

For $r_e = r_{e_2}$, where $\sigma_r(r_e=0)$, the above relation yields the relation

$$R_{es}(r_e) \equiv \int_{r_{e_1}}^{r_e} (\sigma_r - \sigma_0) \frac{1}{\lambda_{ce}^2} \frac{dr_e}{re} = 0$$

From which r_e is found.

The indeterminate pressure, can be found from equilibrium equation

as

$$p(r_e) = \frac{\partial E_k}{\partial E_{nGr}^e} \lambda_{er}^2 + \frac{n}{c_0} \frac{1}{\lambda_{ce}^2} \int_{r_{e_1}}^{r_e} (\sigma_r - \sigma_0) \frac{1}{\lambda_{ce}^2} \frac{dr_e}{re}$$