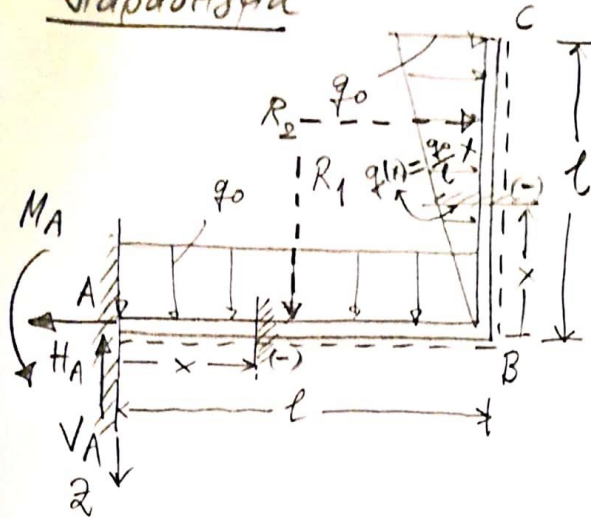


Γραφίσματα

(14.1)



Αντίστροφος έμπειξωρ

$$\sum F_x = 0 \Rightarrow H_A = R_2 = \frac{q_0 l}{2} \text{ kN}$$

$$\sum F_z = 0 \Rightarrow V_A = R_1 = q_0 l \text{ kN}$$

$$\sum M_A = 0 \Rightarrow +M_A - \frac{l}{2} R_1 - \frac{2l}{3} R_2 = 0 \Rightarrow$$

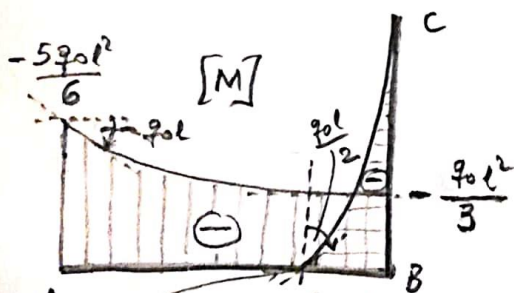
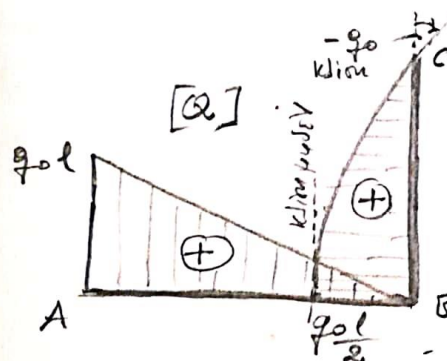
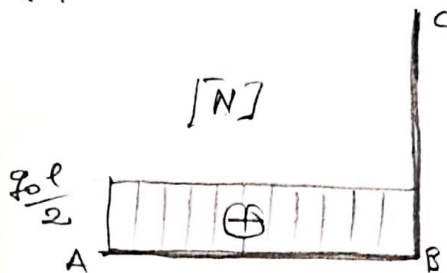
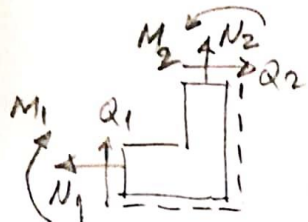
$$\Rightarrow M_A = \frac{l}{2} \left(\frac{q_0 l}{2} + \frac{2q_0 l}{3} \right) = \frac{5q_0 l^2}{6} \text{ kNm}$$

Διαμείδωρ B

$$N_2 = 0 \text{ kN}, Q_2 = \frac{q_0 l}{2} \text{ kN}, M_2 = -\frac{2l}{3} \cdot \frac{q_0 l}{2} = -\frac{q_0 l^2}{3} \text{ kNm}$$

Από ισορροπία στ διαμείδωρ B:

$$N_1 = Q_2 = \frac{q_0 l}{2} \text{ kN}, Q_1 = -N_2 = 0 \text{ kN}, M_1 = M_2 = -\frac{q_0 l^2}{3} \text{ kNm}$$



Αξονικός έστωρ N(x)

$$AB, 0 \leq x \leq l: N(x) = H_A = \frac{q_0 l}{2} \text{ kN} (=N_1 \checkmark)$$

και $\frac{dN}{dx} = -n(x) = 0 \Rightarrow N(x)$ σταθια διαμείδωρ

$$BC, 0 \leq x \leq l: N(x) = 0 \text{ kN} (=N_2 \checkmark), \text{ μάλιστα}$$

Έξωτορ έστωρ Q(x)

$$AB, 0 \leq x \leq l: Q(x) = V_A - q_0 x = q_0 l - q_0 x \text{ kN, σταθ.}$$

$$Q(0) = q_0 l \text{ kN}, Q(l) = 0 \text{ kN} = Q_2 \checkmark \quad (Q'(x) = -q_0 \checkmark)$$

$$BC, 0 \leq x \leq l: Q_2 - \frac{q_0}{l} \frac{x^2}{2} = \frac{q_0 l}{2} - \frac{q_0}{l} \frac{x^2}{2} \text{ kN, σταθ.}$$

$$Q(0) = \frac{q_0 l}{2} \text{ kN} = Q_2 \checkmark, Q(l) = 0 \text{ kN} \checkmark$$

$$Q'(x) = -q(x) = -\frac{q_0}{l} x \frac{\text{kN}}{\text{m}}, Q'(0) = 0 \frac{\text{kN}}{\text{m}} (\text{κλίμακας}), Q'(l) = -\frac{q_0}{l} \frac{\text{kN}}{\text{m}} (\text{κλίμακας})$$

$$Q''(x) = -\frac{q_0}{l} \frac{\text{kN}}{\text{m}^2} (\text{απειρία καθυστέρηση})$$

Ρομής έστωρ M(x)

$$AB, 0 \leq x \leq l: M(x) = M(0) + \int Q(x) dx = -\frac{5q_0 l^2}{6} + \int (q_0 l - q_0 x) dx = -\frac{5q_0 l^2}{6} + q_0 l x - \frac{q_0 x^2}{2} \text{ kNm, μάλιστα}$$

$$M(0) = -\frac{5q_0 l^2}{6} \text{ kNm}, M(l) = -\frac{q_0 l^2}{3} \text{ kNm} = M_2 \checkmark,$$

$$M'(0) = Q(0) = q_0 l \text{ kN(κλίμακας)}, M'(l) = Q(l) = 0 \text{ kN(κλίμακας)},$$

$$M''(x) = -q(x) = -\frac{q_0}{l} \frac{\text{kN}}{\text{m}} (\text{απειρία καθυστέρηση})$$

Από αντιστοιχία στ διαμείδωρ B: κέρδο B

$$BC, 0 \leq x \leq l: M(x) = M_2 + \int Q_2 - \frac{q_0}{l} \frac{x^2}{2} = -\frac{q_0 l^2}{3} + \frac{q_0 l}{2} x - \frac{q_0 x^3}{6l} \text{ kNm, και μάλιστα } M(x) = M_2 + \int Q(x) dx \Rightarrow$$

$$\Rightarrow M(x) = -\frac{q_0 l^2}{3} + \int (\frac{q_0 l}{2} - \frac{q_0}{2l} x^2) dx = -\frac{q_0 l^2}{3} + \frac{q_0 l}{2} x - \frac{q_0 x^3}{6l} \text{ kNm}, M(0) = -\frac{q_0 l^2}{3} \text{ kNm} = M_2 \checkmark, M(l) = 0 \text{ kNm}$$

$$M'(0) = Q(0) = \frac{q_0 l}{2} \text{ kN(κλίμακας)}, M'(l) = Q(l) = 0 \text{ kN(κλίμακας)}, M''(l) = -q(l) = -\frac{q_0}{l} \frac{\text{kN}}{\text{m}} (\text{απειρία καθυστέρηση})$$