

INTEGRATED PLANNING APPROACHES IN HIGHER EDUCATION:
COLLABORATIVE EDUCATIONAL PROTOTYPE TOWARDS
INTEGRATED APPROACHES IN THE PLANNING OF INCLUSIVE,
PEOPLE-CENTRIC AND CLIMATE-RESILIENT CITIES



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InPlanEd



Project: 2022-1-EL01-KA220-HED-000089374 Erasmus+
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commons/pace



παιμετα

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AESOP

πομπή

Tools From Practice: Data Analytics for Evidence based urban planning

Date (to be modified by partners)



InPlanEd



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BEYOND THE FRAME: USING COMPUTER VISION TO UNLOCK THE POTENTIAL OF VIDEO DATA



Computer Vision

Definition

What is computer vision? How can computers understand videos?

Computer vision is a field of artificial intelligence and computer science that focuses on enabling machines to interpret and understand visual information from the world around us.

These algorithms analyze the visual content, including shapes, colors, motion and extract features.

These features can be labeled and then used to train AI models to recognize objects, actions or scenes within a videos using ML techniques.

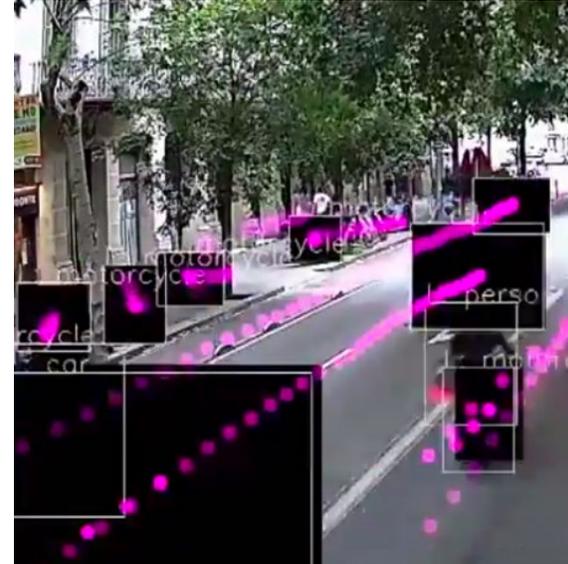
Workflow



Data Collection



Data Pre-Processing



AI Algorithm

20220706	'time'	19:24:32	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:24:33	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:24:34	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:24:35	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:24:36	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:24:37	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:24:38	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:24:39	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:24:40	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:24:41	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:24:42	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:24:43	'cars'	7	'person'	8	'bicycle'
20220706	'time'	19:24:44	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:24:45	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:24:46	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:25:03	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:25:04	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:25:14	'cars'	9	'person'	8	'bicycle'
20220706	'time'	19:25:15	'cars'	9	'person'	8	'bicycle'
20220706	'time'	19:25:34	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:25:35	'cars'	7	'person'	7	'bicycle'
20220706	'time'	19:25:38	'cars'	7	'person'	8	'bicycle'
20220706	'time'	19:25:43	'cars'	8	'person'	8	'bicycle'
20220706	'time'	19:25:44	'cars'	8	'person'	7	'bicycle'
20220706	'time'	19:25:45	'cars'	7	'person'	8	'bicycle'
20220706	'time'	19:25:51	'cars'	6	'person'	8	'bicycle'
20220706	'time'	19:25:52	'cars'	5	'person'	7	'bicycle'
20220706	'time'	19:25:53	'cars'	6	'person'	8	'bicycle'
20220706	'time'	19:25:54	'cars'	7	'person'	8	'bicycle'
20220706	'time'	19:25:55	'cars'	7	'person'	6	'bicycle'

Data Post-Processing

DATA COLLECTION

Importance and requirements

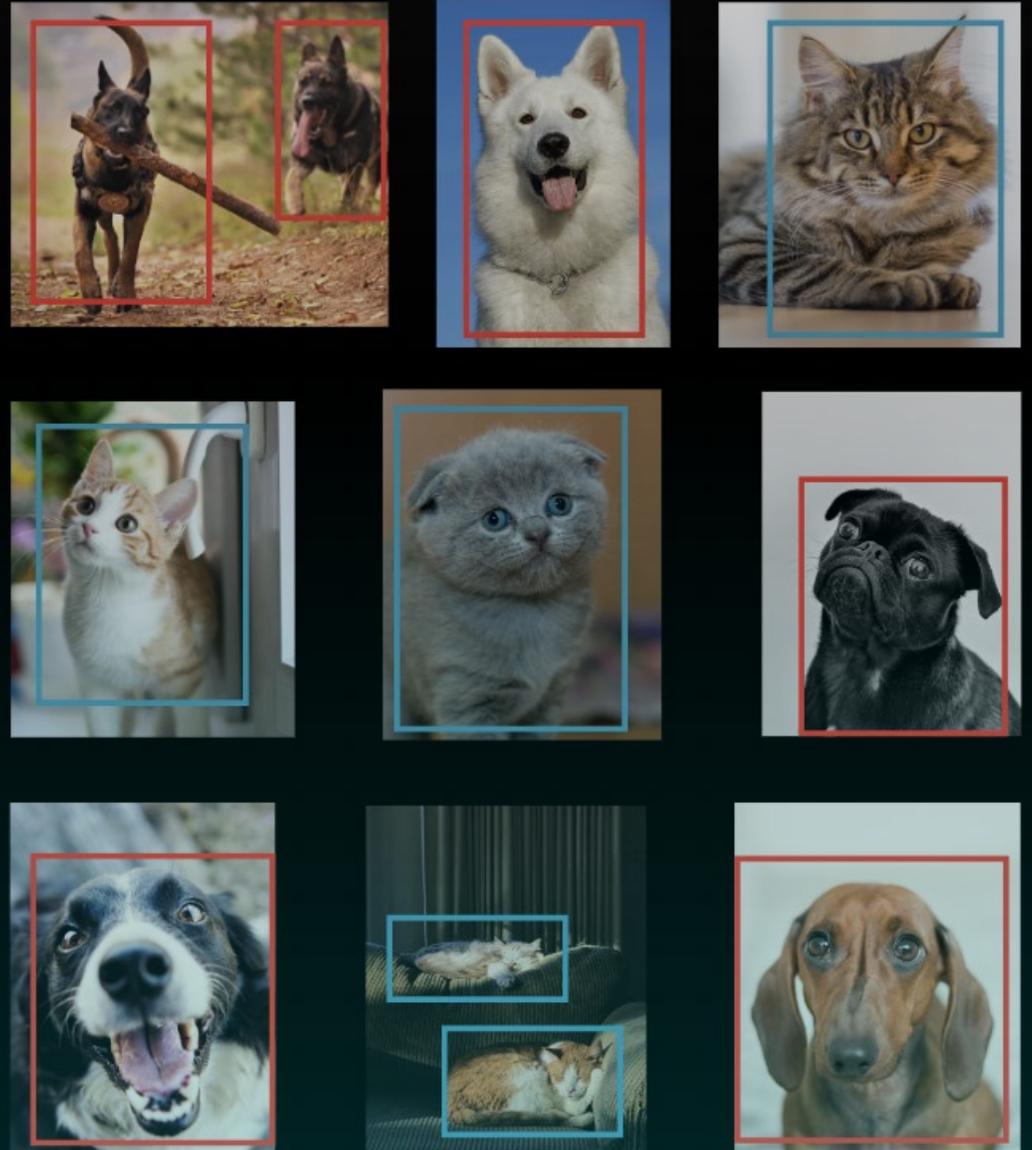
- Key factor for the final performance of the algorithm.
- Why is it so important?
 - Training
 - Specific project data

- Dataset requirements:
 - Large amounts
 - Variety
 - Balanced
 - Representative
 - Well labeled



VERY EXPENSIVE

Image: Cats and dogs dataset
Source: Pexel





DATA COLLECTION

Open Source Datasets

Common datasets and licences:

- **ImageNet:** data is available for free to researchers for non-commercial use
 - 1,281,167 training images, 50,000 validation images and 100,000 test images
 - 1000 classes
- **Kinetics:** Creative Commons Attribution 4.0 International License
 - 500k video clips of human actions
 - 600 different human actions labelled
- **COCO:** Creative Commons Attribution 4.0 International License
 - >200.000 images labelled
 - 80 classes
- **Youtube-8M:** Creative Commons Attribution 4.0 International (CC BY 4.0) license
 - 6.1 Million videos, 237K human label verified, 1000 classes

Image: Set of labelled images from COCO dataset.
Source: COCO dataset

DATA PRE-PROCESSING

Image and Video processing

The purpose of data preprocessing is to clean, transform, and restructure data to make it suitable for analysis.

- Image processing
- Video processing:
 - Video sampling
 - Video rescaling
 - Video Normalization
 - Video Encoding
 - Stacking frames into 3D tensor with dimen (#frames, height, width)
 - 2D CNN to capture spatial dependencies
 - 3D CNN to capture spatial and temporal dependencies

*Image: Car image
Source: Pexels*



Image Segmentation: Binary

Image Enhancement



Image Filtering: Laplacian

Image Restoration

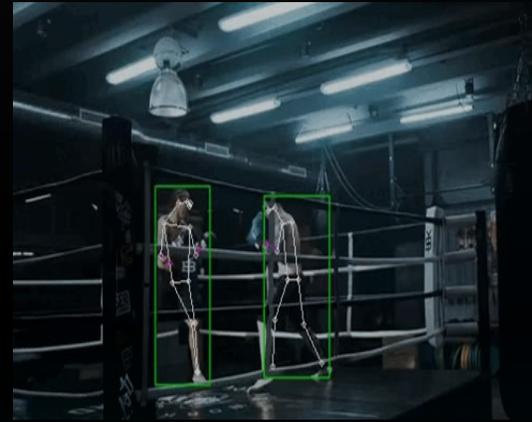
ALGORITHM

Types of algorithms

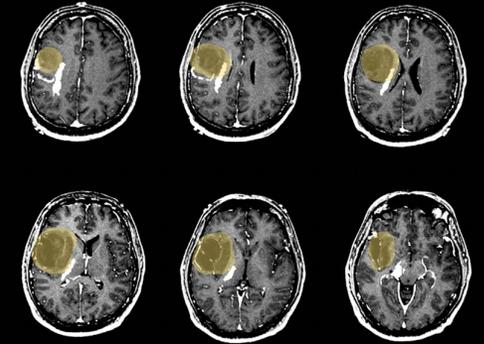
Deep Learning Algorithms:

- Object detection
 - Class identification
 - Disease detection
- Pose estimation
 - Pose recognition
- Semantic Segmentation
- Instance segmentation
- Face recognition
- Object tracking

Image: Different Computer Vision applications
Source: Pexel



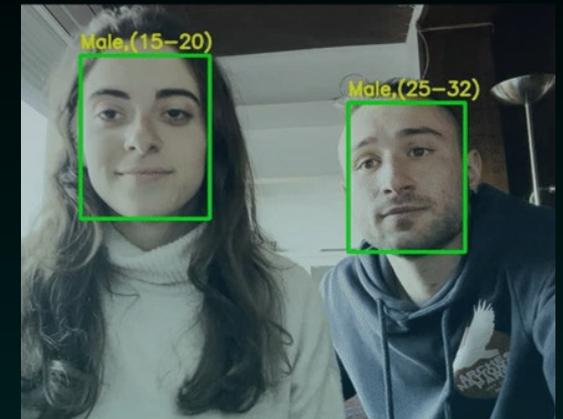
HUMAN POSE ESTIMATION



DISEASE DETECTION



SEMANTIC SEGMENTATION
AND TRACKING



FACE DETECTION: GENDER AND
AGE

DATA POST-PROCESSING

Reduction of stored data

- Clean output data:
 - Non-maximum suppression
 - Thresholding
 - Filtering
- Extract meaning from data
- Create visualizations

Website: noumena.io

REAL CASE SCENARIO
URBAN MAPPING



URBAN MAPPING

Monitoring Public Spaces

Analyse spatial dynamics from video data recorded by the urban municipality of Barcelona, specifically the Department of Urban Development, Barcelona Regional.

The scope of this research is to **understand spatial dynamics in a public space, informing urban transformation and future planning decisions.**

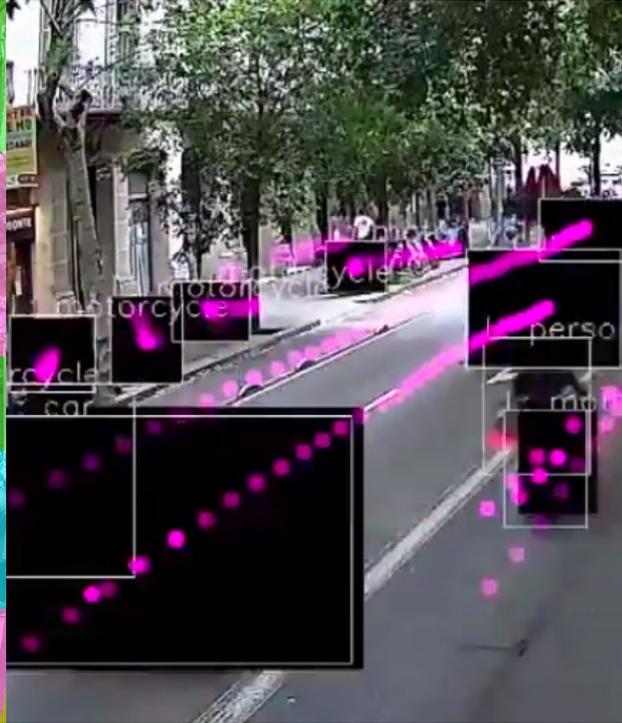
Client: Barcelona Regional

Data Analytics: Noumena.

Noumena credits :

Aldo Sollazzo, Soroush Garivani, Oriol Arroyo, Cosme Pommier, Paula Osés, Salvador Calgua

поцмена



ay	:	20220706	,	'time	':	19:24:32	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:24:33	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:24:34	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:24:35	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:24:36	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:24:37	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:24:38	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:24:39	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:24:40	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:24:41	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:24:42	,	'cars	':	8	,	'person	':	7	,	'bicycl
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ay	:	20220706	,	'time	':	19:24:46	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:25:03	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:25:04	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:25:14	,	'cars	':	9	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:25:15	,	'cars	':	9	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:25:34	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:25:35	,	'cars	':	7	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:25:38	,	'cars	':	7	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:25:43	,	'cars	':	8	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:25:44	,	'cars	':	8	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:25:45	,	'cars	':	7	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:25:51	,	'cars	':	6	,	'person	':	8	,	'bicycl
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ay	:	20220706	,	'time	':	19:25:57	,	'cars	':	7	,	'person	':	7	,	'bicycl
ay	:	20220706	,	'time	':	19:26:00	,	'cars	':	7	,	'person	':	8	,	'bicycl
ay	:	20220706	,	'time	':	19:26:03	,	'cars	':	6	,	'person	':	8	,	'bicycl

DATA COLLECTION

DATA PRE-PROCESSING

AI ALGORITHM

DATA POST-PROCESSING

DATA COLLECTION

General



TRAINING DATA



PREDICTION DATA



DATA COLLECTION

Training data - COCO

URL: <https://cocodataset.org/#explore>

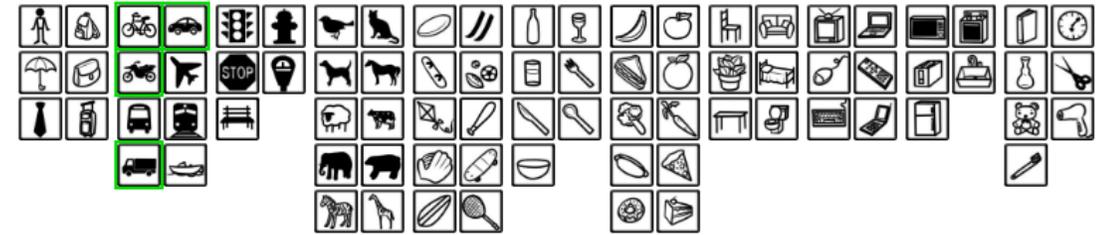
This is the COCO dataset webpage where you can explore the different classes and understand how the labelling is made.

Classes:

- Cars
- Bikes
- Motorbikes
- Trucks
- Pedestrians

COCO Explorer

COCO 2017 train/val browser (123,287 images, 886,284 instances). Crowd labels not shown.



car x motorcycle x bicycle x truck x

82 results



DATA COLLECTION

COCO - Folder structure

In this representation, the top-level directory is `coco/`. Within this directory, there are three subdirectories : `annotations/`, `train2017/`, `val2017/`, and `test2017/`.

The `annotations/` directory contains **JSON** files that specify the annotations for each image in the dataset, including the object detection and segmentation annotations, as well as annotations for captions and person keypoints .

The `train2017/`, `val2017/`, and `test2017/` directories contain the images for the training, validation, and test splits of the dataset, respectively . The images are stored in JPEG format and are named according to their image IDs.

Finally, there are two additional files in the top-level directory : `licenses.txt`, which contains the license agreements for the dataset, and `README.txt`, which provides a brief description of the dataset and instructions for using it.

```
coco/
├── annotations/
│   ├── instances_train2017.json
│   ├── instances_val2017.json
│   ├── instances_test2017.json
│   ├── captions_train2017.json
│   ├── captions_val2017.json
│   ├── person_keypoints_train2017.json
│   └── person_keypoints_val2017.json
├── train2017/
│   ├── 000000000009.jpg
│   ├── 000000000025.jpg
│   ├── ...
│   └── 000000581921.jpg
├── val2017/
│   ├── 000000000139.jpg
│   ├── 000000000285.jpg
│   ├── ...
│   └── 000000581921.jpg
├── test2017/
│   ├── 000000000001.jpg
│   ├── 000000000002.jpg
│   ├── ...
│   └── 000000581929.jpg
├── licenses.txt
└── README.txt
```

DATA COLLECTION

COCO - JSON Annotations

The annotations field:

- `id`: A unique identifier for the object annotation.
- `image_id`: The identifier of the image that the object belongs to.
- `category_id`: The identifier of the category that the object belongs to.
- `bbox`: A list of four values that specify the bounding box of the object. The values are [x, y, width, height]

The images field:

- `id`: The identifier of the image.
- `width`: The width of the image in pixels.
- `height`: The height of the image in pixels.
- `file_name`: The file name of the image.

The categories field:

- `id`: The identifier of the category.
- `name`: The name of the category.
- `supercategory`: (Optional) The name of the supercategory that the category belongs to.

```
{
  "annotations": [
    {
      "id": 1,
      "image_id": 1234,
      "category_id": 1,
      "bbox": [155, 200, 65, 60]
    },
    {
      "id": 2,
      "image_id": 1234,
      "category_id": 3,
      "bbox": [320, 190, 110, 50]
    },
    {
      "id": 3,
      "image_id": 1234,
      "category_id": 2,
      "bbox": [100, 300, 100, 100]
    }
  ],
  "images": [
    {
      "id": 1234,
      "width": 640,
      "height": 480,
      "file_name": "image1234.jpg"
    }
  ],
  "categories": [
    {"id": 1, "name": "person"},
    {"id": 2, "name": "motorcycle", "supercategory": "vehicle"},
    {"id": 3, "name": "car", "supercategory": "vehicle"}
  ]
}
```



Website: noumena.io

DATA COLLECTION

Prediction data

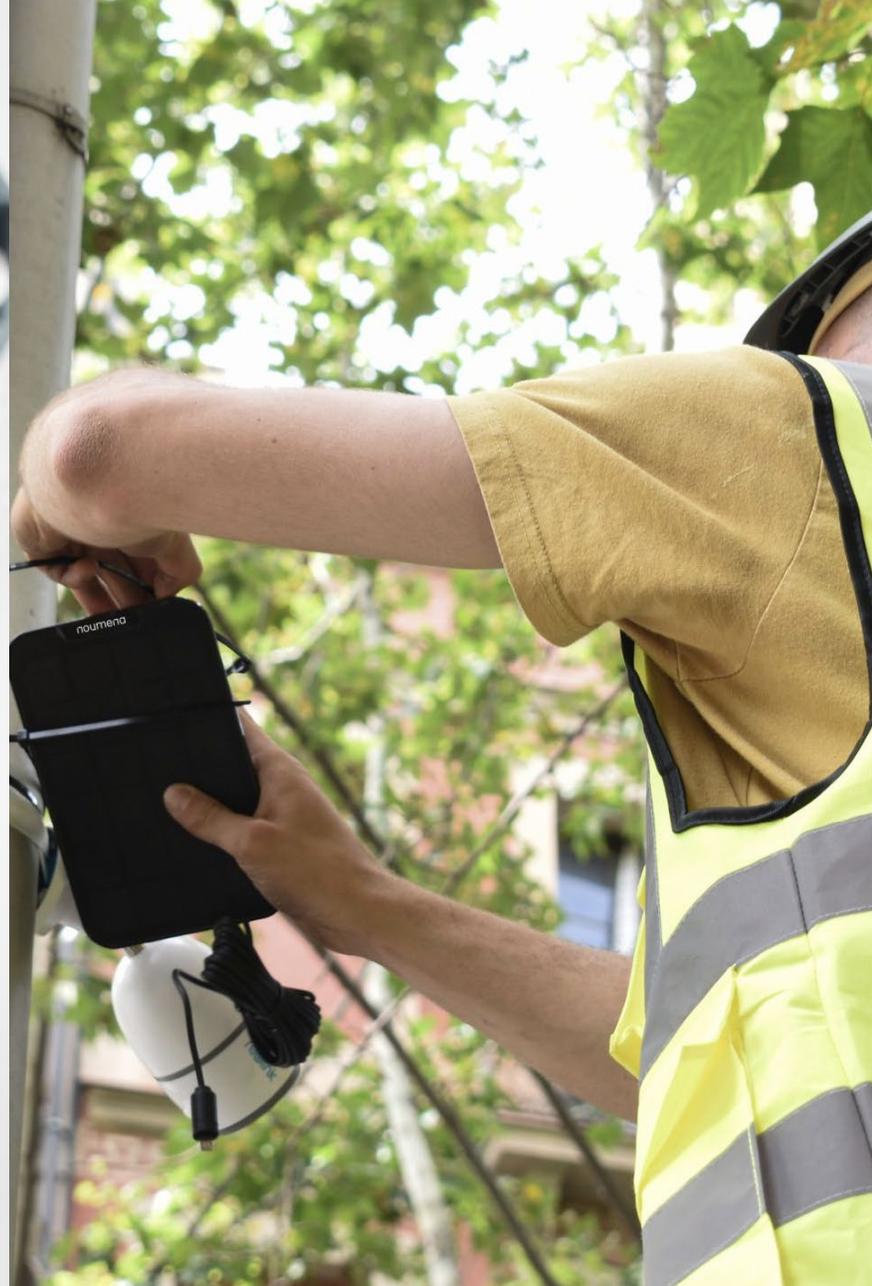
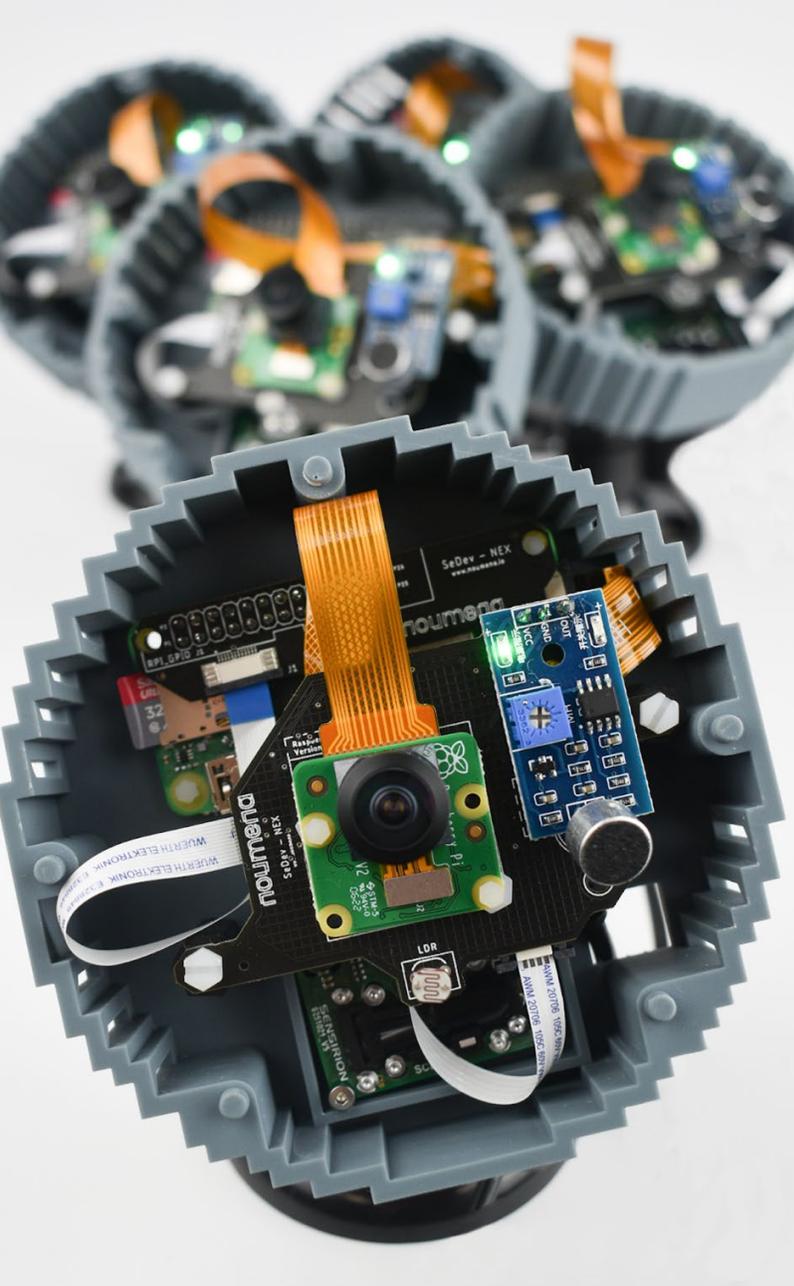
Number of cameras: 7

Camera sensor: RGB

Time: 3 days (Monday, Thursday, Sunday) - 24 hours/day

Streets: Super illa (Consell de cent), nearby streets (valencia)

Amount of data: 600GB

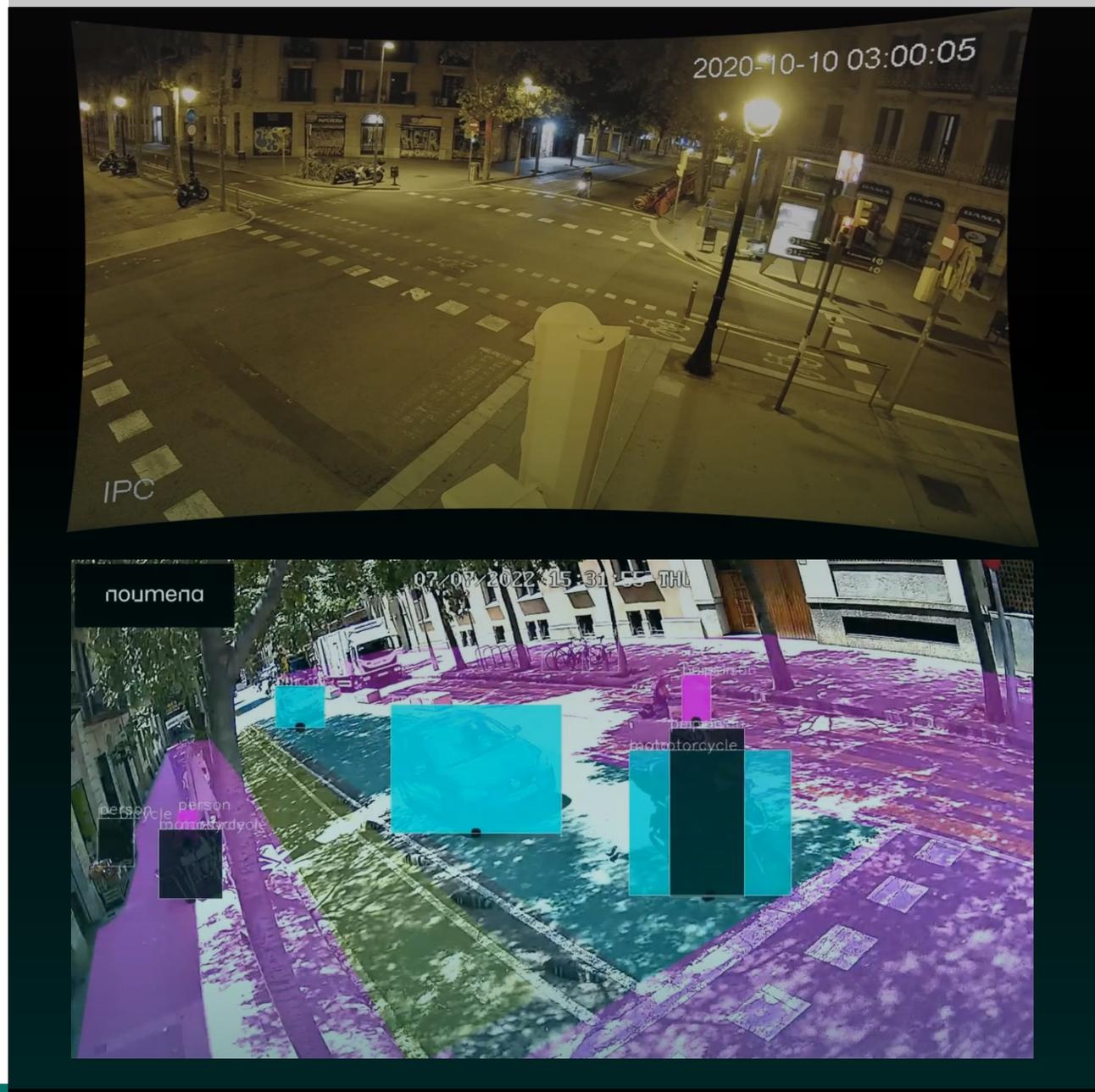


DATA PRE-PROCESSING

Prediction Data

- Reduce frame rate (fps)
- Correct distortion with image calibration
- Create Corridors

Website: noumena.io





ALGORITHM

OBJECT DETECTION AND TRACKING

Object detection algorithm: YOLOv7

- Open Source
- Developed by ultralytics
- Training data: COCO dataset
- Classes detected:
 - Cars
 - Pedestrians
 - Bicycles
 - Motorbikes
 - Small trucks

Tracker algorithm: Norfair

- Customizable lightweight Python library for real-time multi-object tracking

Custom made algorithm to extract data from the algorithms and counter implementation



ALGORITHM WORKFLOW

- Input encoded videos
- Object detection algorithm
- Tracking algorithm
- Extract data from videos:
 - Type of class (cars, person, ...)
 - The x,y position
 - The time
- Implement counter
- Save data into database

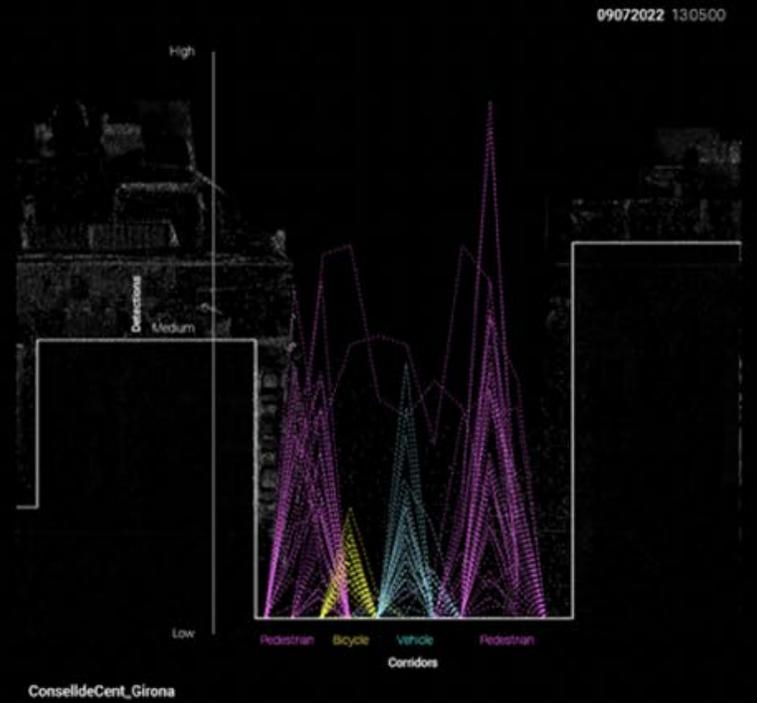
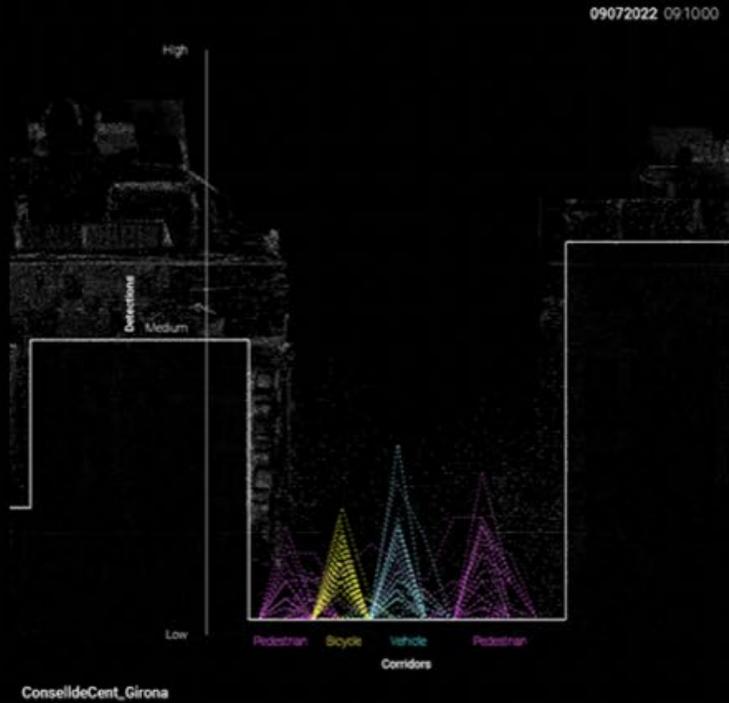
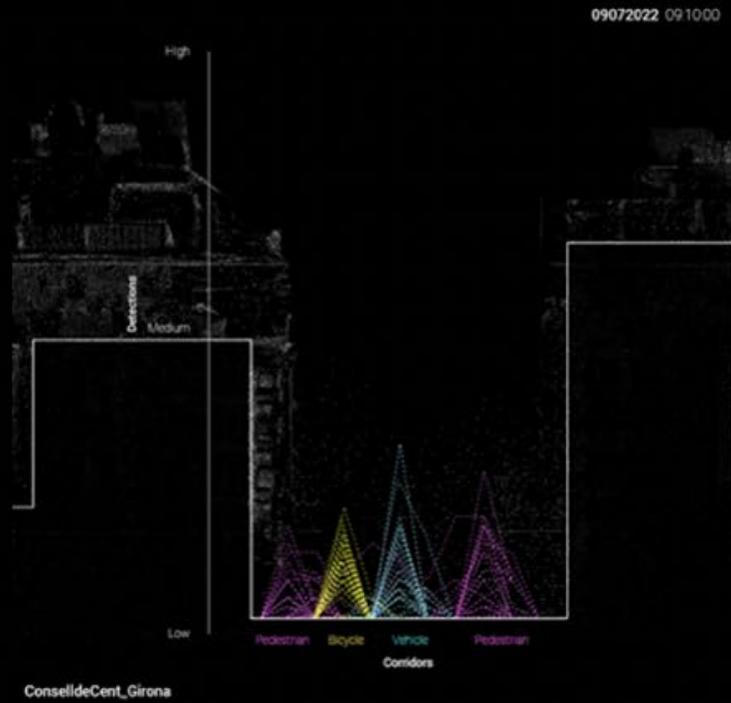


DATA POST-PROCESSING

General

- Clean data
- Create visualizations
- Ground truth comparison

```
ay' : '20220706', 'time' : '19:24:32', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:24:33', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:24:34', 'cars' : 8, 'person' : 7, 'bicycl
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ay' : '20220706', 'time' : '19:24:37', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:24:38', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:24:39', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:24:40', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:24:41', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:24:42', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:24:43', 'cars' : 7, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:24:44', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:24:45', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:24:46', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:03', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:25:04', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:25:14', 'cars' : 9, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:15', 'cars' : 9, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:34', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:25:35', 'cars' : 7, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:25:38', 'cars' : 7, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:43', 'cars' : 8, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:44', 'cars' : 8, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:25:45', 'cars' : 7, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:51', 'cars' : 6, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:52', 'cars' : 5, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:25:53', 'cars' : 6, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:54', 'cars' : 7, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:25:55', 'cars' : 7, 'person' : 6, 'bicycl
ay' : '20220706', 'time' : '19:25:56', 'cars' : 7, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:25:57', 'cars' : 7, 'person' : 7, 'bicycl
ay' : '20220706', 'time' : '19:26:00', 'cars' : 7, 'person' : 8, 'bicycl
ay' : '20220706', 'time' : '19:26:03', 'cars' : 6, 'person' : 8, 'bicycl
```



Data Post-Processing

GROUND TRUTH COMPARISON

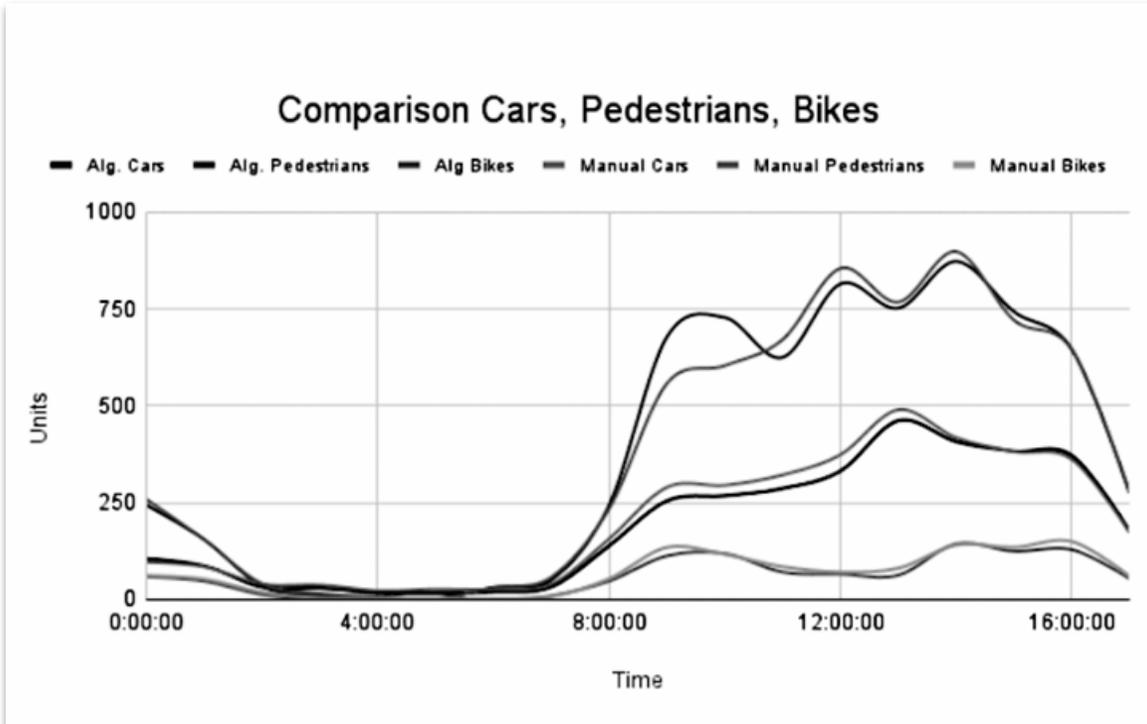


Chart 5: Comparison of algorithm and manual count for cars, bikes and pedestrians.

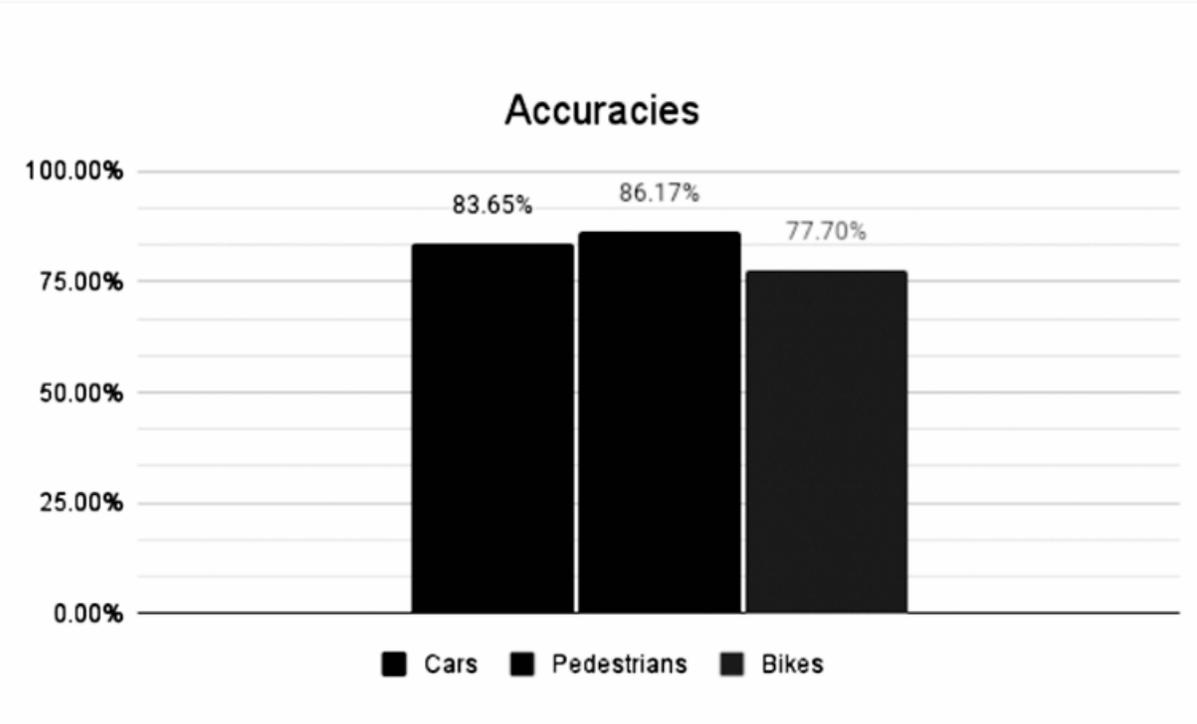


Chart 6: Accuracies for detection of cars, bikes and pedestrians.



LESSONS LEARNED

OBJECT DETECTION AND TRACKING

- Video processing timings
- Higher camera definition
- Corridors
- Edge computing

thank you!



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INTEGRATED PLANNING APPROACHES IN HIGHER EDUCATION:
COLLABORATIVE EDUCATIONAL PROTOTYPE TOWARDS
INTEGRATED APPROACHES IN THE PLANNING OF INCLUSIVE,
PEOPLE-CENTRIC AND CLIMATE-RESILIENT CITIES

ποικτεπα



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