



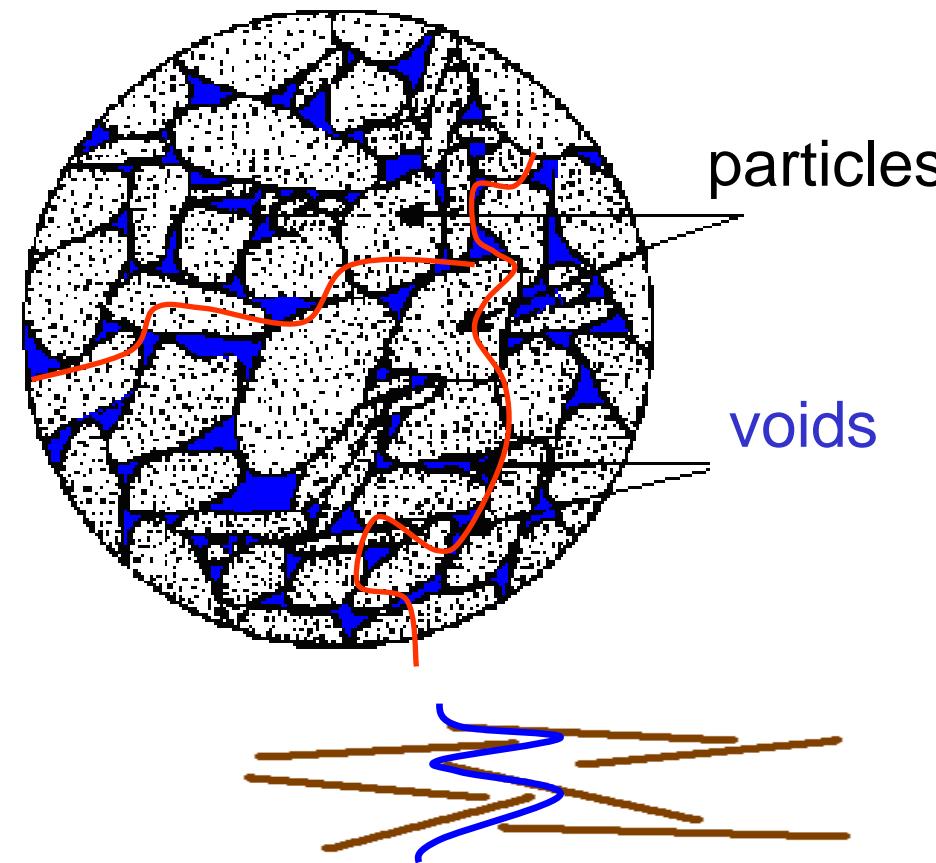
SEEPAGE:steady-state groundwater flow

ΥΔΑΤΙΚΗ ΡΟΗ ΔΙΑΜΕΣΟΥ ΕΔΑΦΙΚΟΥ ΥΛΙΚΟΥ

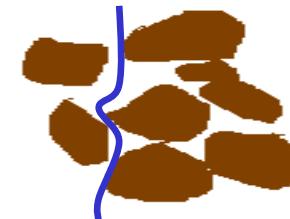
Professor V.N. Georgiannou

Permeable soils

The apparent **velocity** with which groundwater moves through the bulk of the porous medium is called seepage velocity

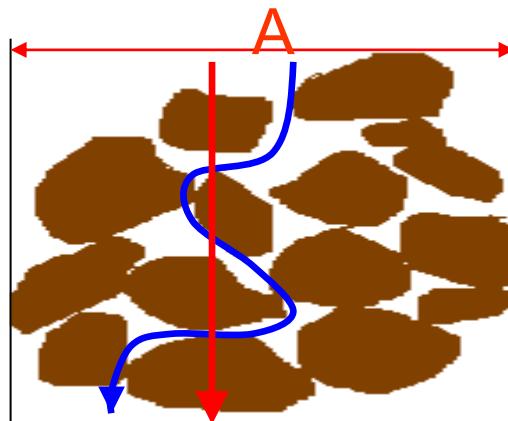


clay
 $K < 10^{-7}$ m/s



sand
 $K > 10^{-2}$ m/s

Flow velocity or flux



■ Gross cross sectional area of flow $u=Q/A$

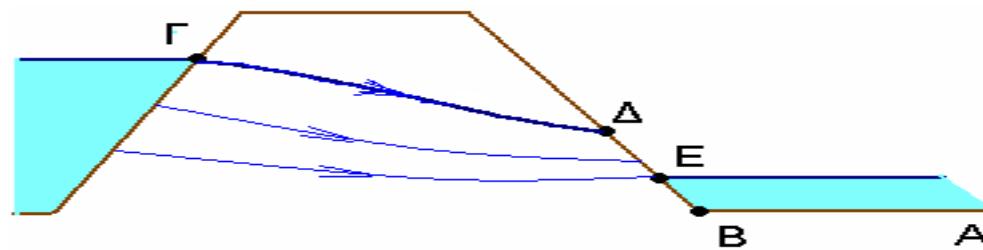
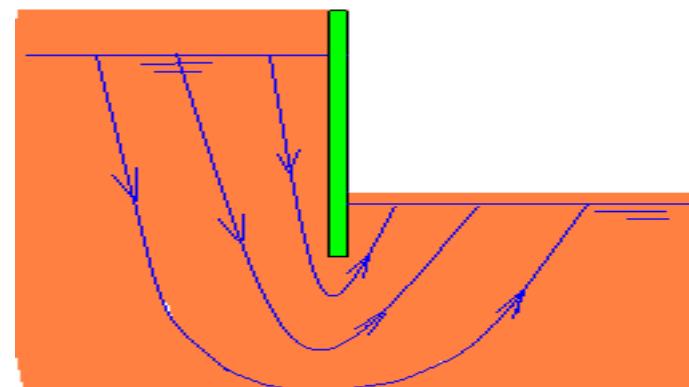
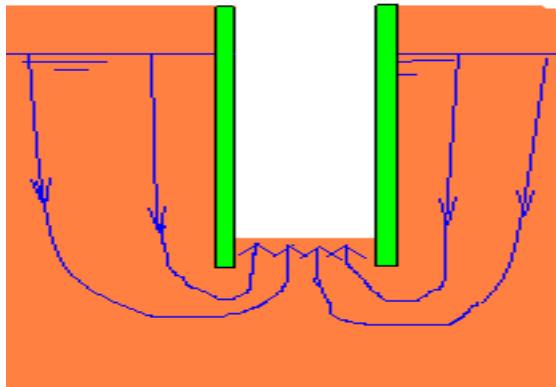
■ Effective cross sectional area of voids
 $U_s=Q/A_{\text{voids}}$



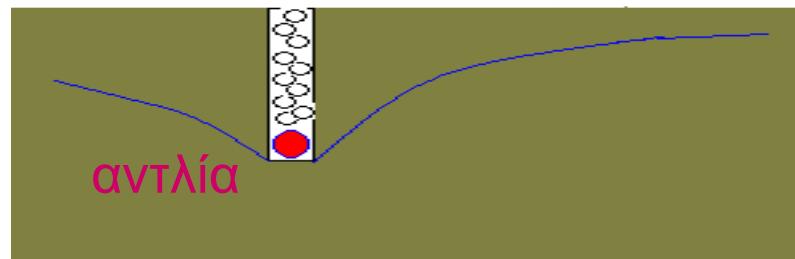
Avoids / A = Vvoids / V = n =
porosity

$$U_s = u / n$$

Flow problems

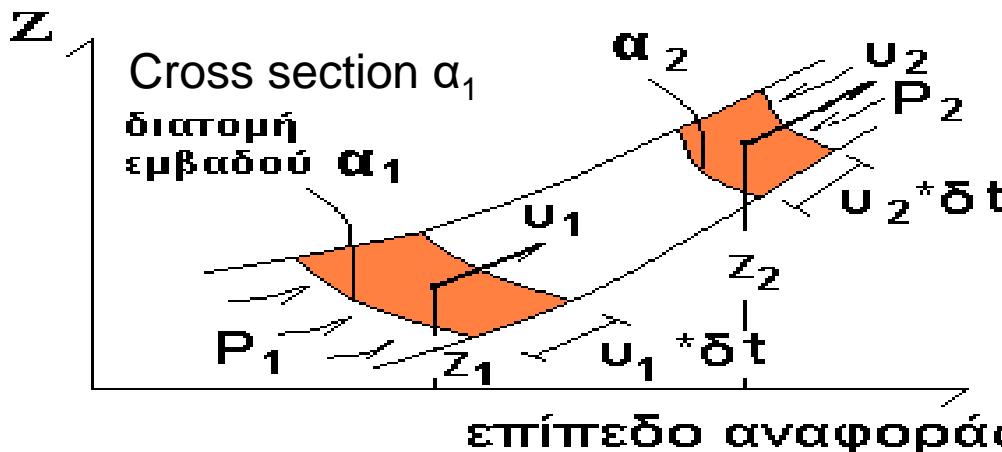


$\Sigma.Y.O$



ONE DIMENSIONAL FLOW

Variables at points 1 & 2:
pressure, speed, height



$$P_1 \alpha_1 v_1 \delta t V - P_2 \alpha_2 v_2 \delta t = \rho V g z_2 + \frac{1}{2} \rho V (v_2)^2 - (\rho V g z_1 + \frac{1}{2} \rho V (v_1)^2)$$

Bernoulli

Pressure at elevation 1

$$\frac{P_1}{\gamma_w} + Z_1 + \frac{v_1^2}{2 * g} = \frac{P_2}{\gamma_w} + Z_2 + \frac{v_2^2}{2 * g}$$

Principle of energy conservation
 $\sim 10^{-6} \mu$

Potential+kinetic

$$h = \frac{u}{\gamma_w} + z + \Delta h$$

Total head

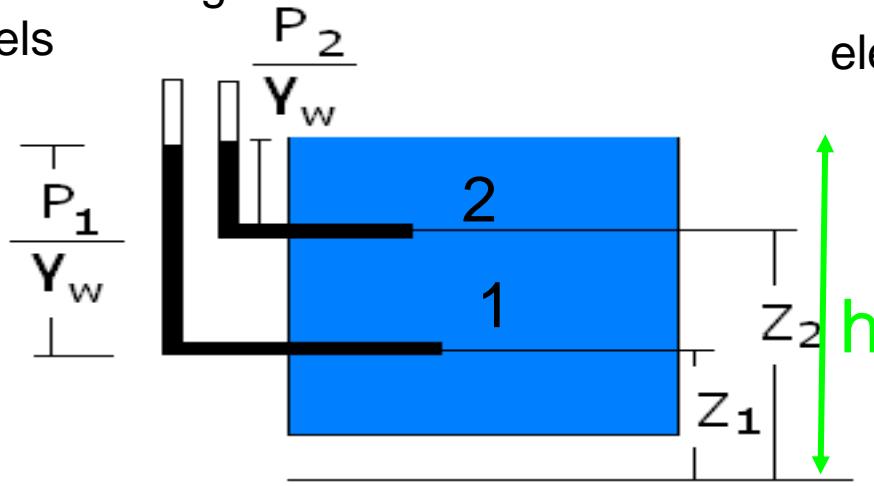
piezometric + geometric head

head loss

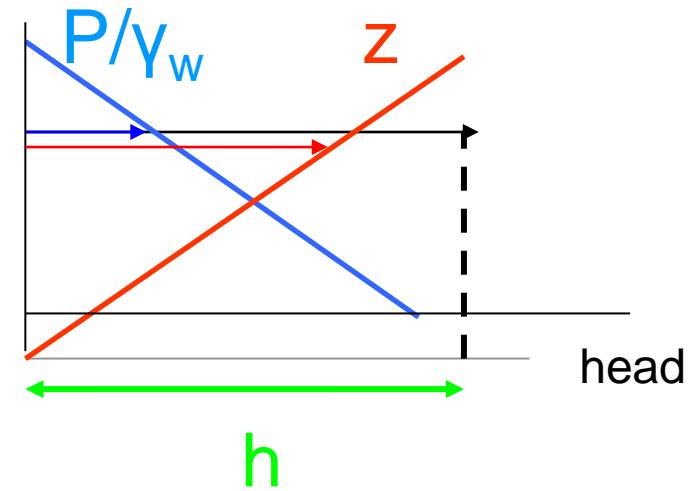
control groundwater movement

Total head in static water

Communicating
vessels

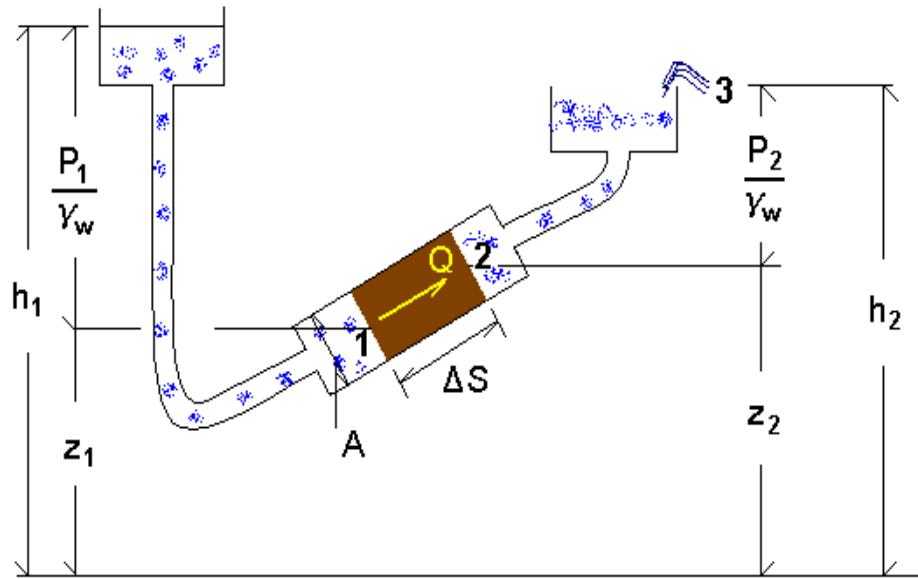


elevation



- 1: $P_1/\gamma_w + z_1 =$
- 2: $P_2/\gamma_w + z_2 = h$

DARCY's Law



$$\frac{Q}{A} = k \cdot \frac{h_1 - h_2}{\Delta S} \quad \frac{Q}{A} = v = \text{Flow velocity}$$

$$i = \frac{h_2 - h_1}{\Delta S} = \begin{array}{l} \text{Hydraulic gradient} \\ \text{υδραυλική κλίση} \end{array}$$

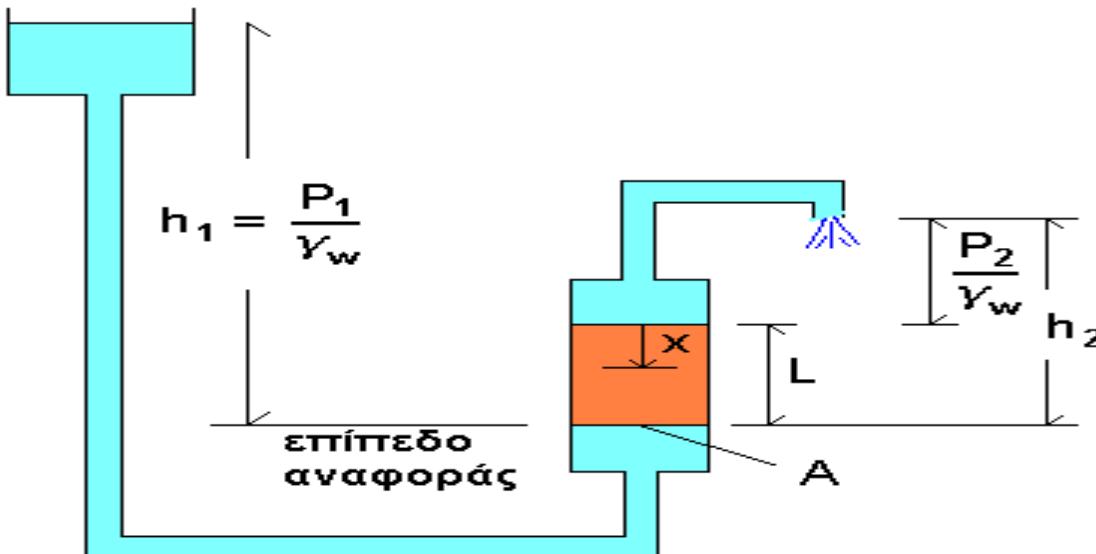
$$v = -k \cdot i$$

και

$$Q = -k \cdot i \cdot A$$

k = hydraulic conductivity, permeability (in velocity units)

Critical Hydraulic Gradient



$$Q = A \cdot k \cdot \frac{h_1 - h_2}{L} = A \cdot k \cdot (-i)$$

$$\sigma_v = p_2 + \gamma \cdot x$$

$$p_2 + \frac{p_1 - p_2}{L} \cdot x$$

$$\frac{p_1 - p_2}{L} = \gamma$$

$$i_{crit} = \frac{h_2 - h_1}{L} = \frac{\frac{p_2}{\gamma_w} + L - \frac{p_1}{\gamma_w}}{L} = 1 - \frac{p_1 - p_2}{\gamma_w \cdot L}$$

$$-i_{crit} = \frac{\gamma}{\gamma_w} - 1$$

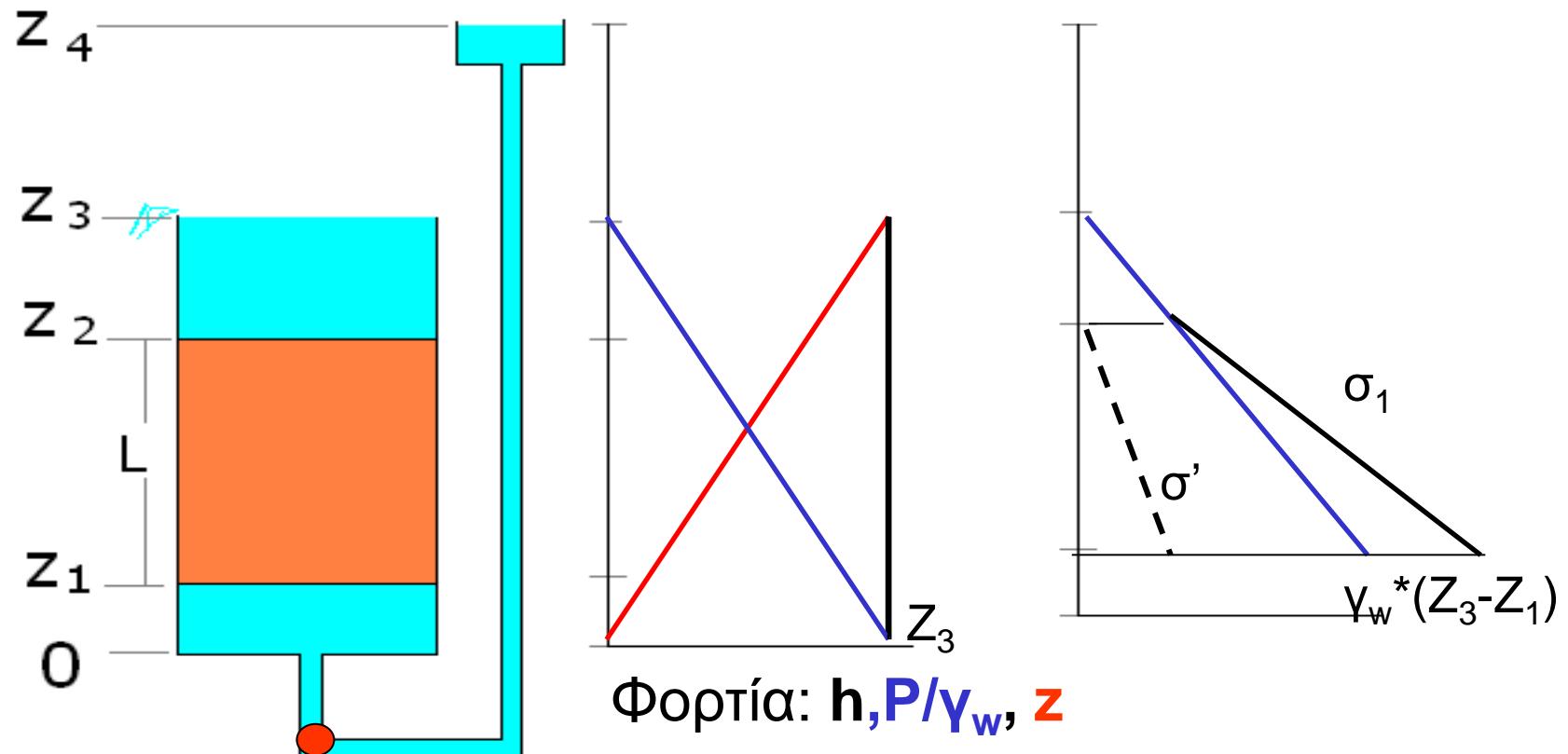


QUICK SAND



1. Sand has no strength due to LIQUEFACTION or due to SOIL PIPING
2. Can we drown in quick sand?

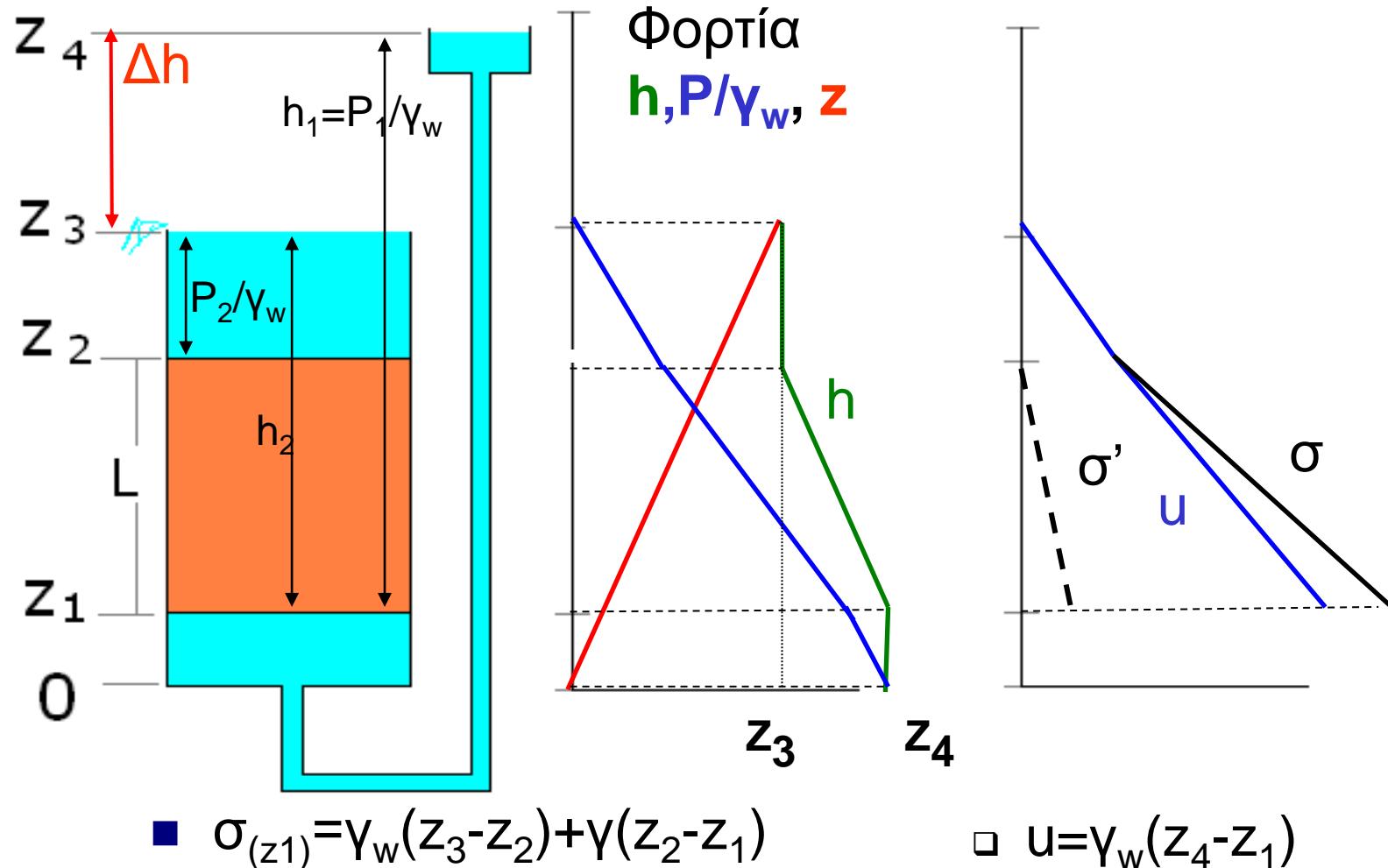
Effective stresses under hydrostatic conditions



- $\sigma'_{(z_1)} = \gamma_w(z_3 - z_2) + \gamma(z_2 - z_1) - \gamma_w(z_3 - z_1) = \gamma(z_2 - z_1) - \gamma_w(z_2 - z_1) = \gamma'L$

$$\xleftarrow{\sigma_{(z_1)}} \qquad \xleftarrow{P/\gamma_w}$$

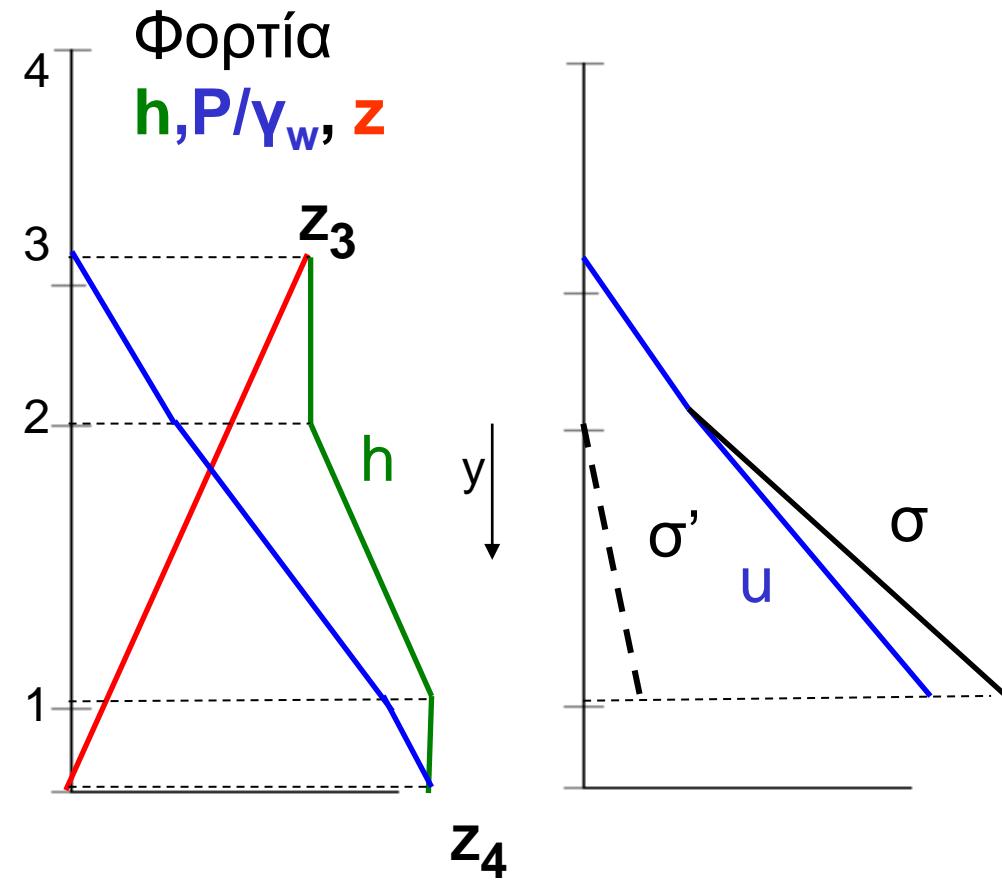
Effective stresses under seepage conditions



$$\sigma'_{(z_1)} = \gamma(z_2 - z_1) - \gamma_w(z_2 - z_1) - \gamma_w(z_4 - z_3) = \gamma'L - \gamma_w\Delta h$$

Effective stresses under seepage conditions

- $\sigma = \gamma_w(z_3 - z_2) + \gamma^*y$
- $u = \gamma_w(z_3 - z_2) + \gamma_w((z_4 - z_1) - (z_3 - z_2)) * y/L$
- $\sigma' = \sigma - u = \gamma^*y - \gamma_w(\Delta h - (z_2 - z_1)) * y/L$



$$\begin{aligned}\sigma' &= (\gamma^*y - \gamma_w \Delta h * y/L - \gamma_w * L * y/L) = (\gamma' - \gamma_w \Delta h/L)y \\ &= 0 \rightarrow i_{cr} = \gamma'/\gamma_w\end{aligned}$$

$$h = u / \gamma_w + z$$

Total head controls the flow of underground water

$$U = -K * i$$

Permeability in velocity units

$$i = \Delta h / L$$

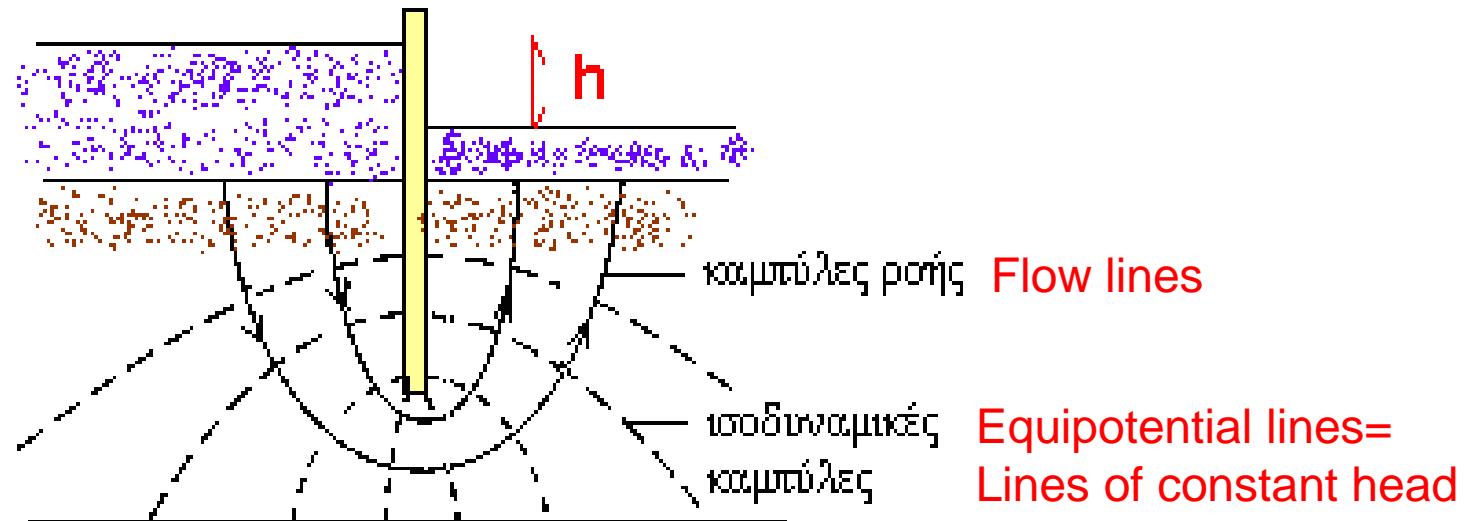
Hydraulic gradient

$$\sigma' = (\gamma' - \gamma_w \Delta h / L) y$$
$$= 0 \rightarrow i_{cr} = \gamma' / \gamma_w$$

Effective stresses under seepage conditions

Critical hydraulic gradient

Two dimensional seepage



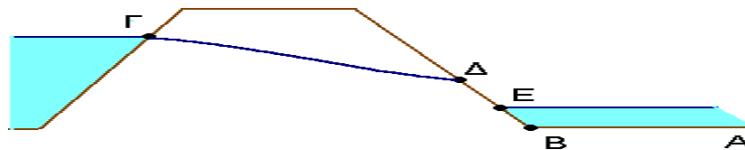
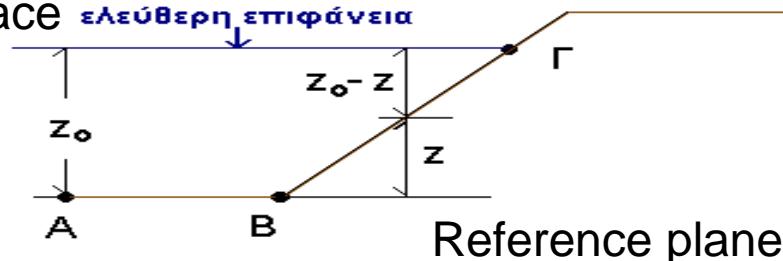
a graphical representation of two-dimensional steady-state groundwater flow equation

$$\frac{\partial^2 h}{\partial z^2} + \frac{\partial^2 h}{\partial x^2} = 0$$

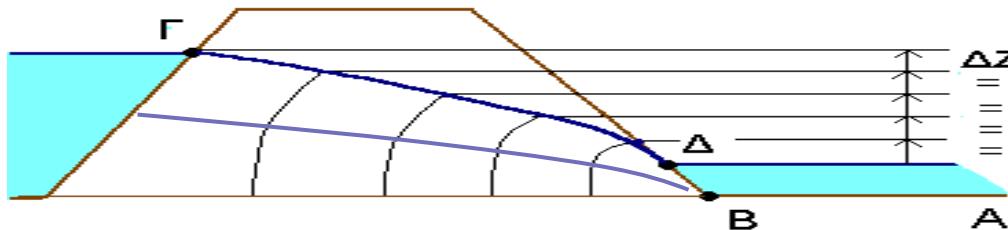
- Under two dimensional seepage the sum of the change in hydraulic gradient in the two directions is zero

Boundary conditions

Free surface ελεύθερη επιφάνεια



Freatic line



Each interval between 2 equipotentials corresponds to a head loss Δh equal to $1/N$ of the total head loss h through the soil: $\Delta h = h/N$

$$h = \frac{P}{\gamma_w} + z$$

$$P = \gamma_w \cdot (z_o - z)$$

$$h = z_o - z + z = z_o$$

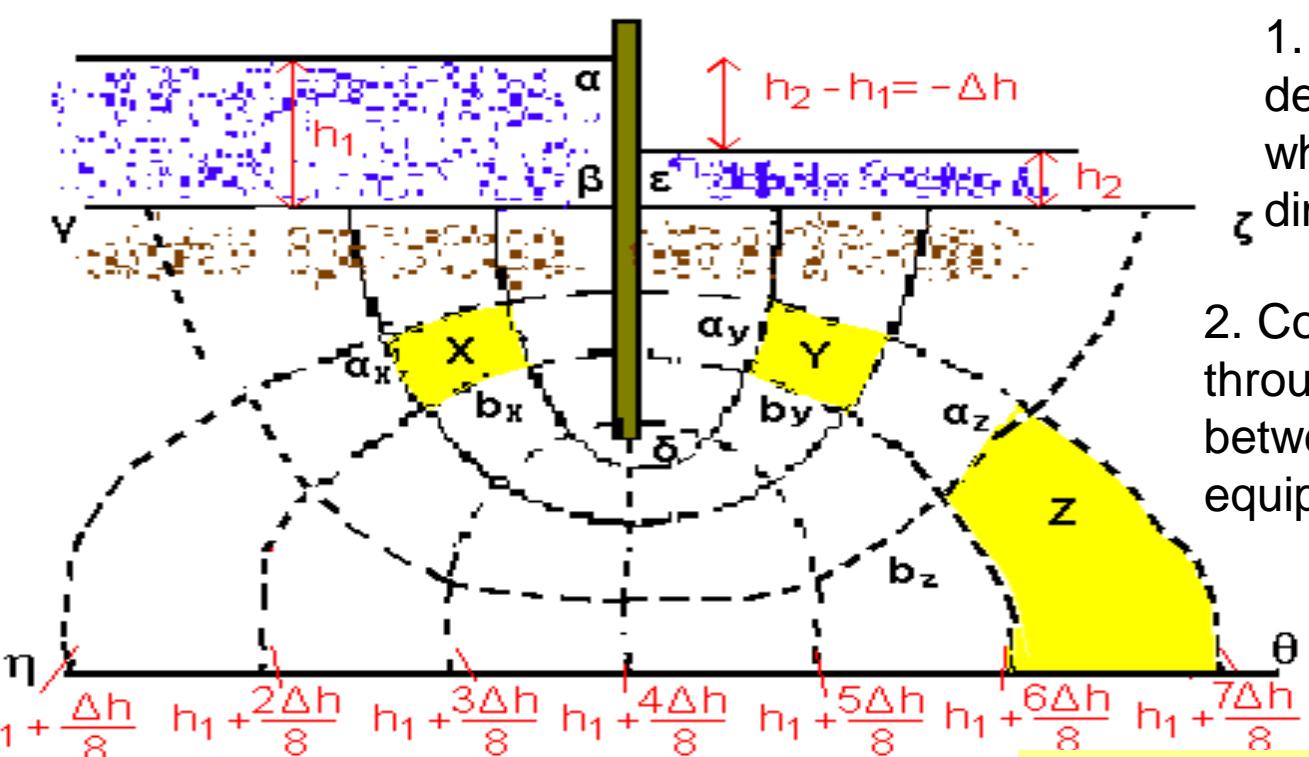
$$h = \frac{P}{\gamma_w} + z$$

$$P = 0$$

$$h = z$$

Equipotentials intersect the freatic line at constant drops in height

Ισοδυναμικές τέμνουν τη φρεατική γραμμή ανά ίσες μεταβολές στάθμης



1. A pair of flow lines define a tube (channel) where flow is one dimensional

2. Consider the flow through an area delimited between 2 flow and 2 equipotential lines

$$q_x = -k \cdot \frac{-\frac{\Delta h}{8}}{a_x} \cdot b_x \cdot 1 \quad q_y = -k \cdot \frac{-\frac{\Delta h}{8}}{a_y} \cdot b_y \cdot 1 \quad q_z = -k \cdot \frac{-\frac{\Delta h}{8}}{a_z} \cdot b_z \cdot 1$$

$$q_x = q_y \rightarrow \frac{b_x}{a_x} = \frac{b_y}{a_y} \text{ eiv} \quad \frac{b_z}{a_z} = \frac{b_y}{a_y} \longrightarrow q_z = q_y$$

$$q_x = q_y = q_z \quad N_{\rho} = \text{Number of flow channels (4)}$$

$$\text{Eiv} \quad N_{\delta} = \text{Number of drops in head (8)}$$

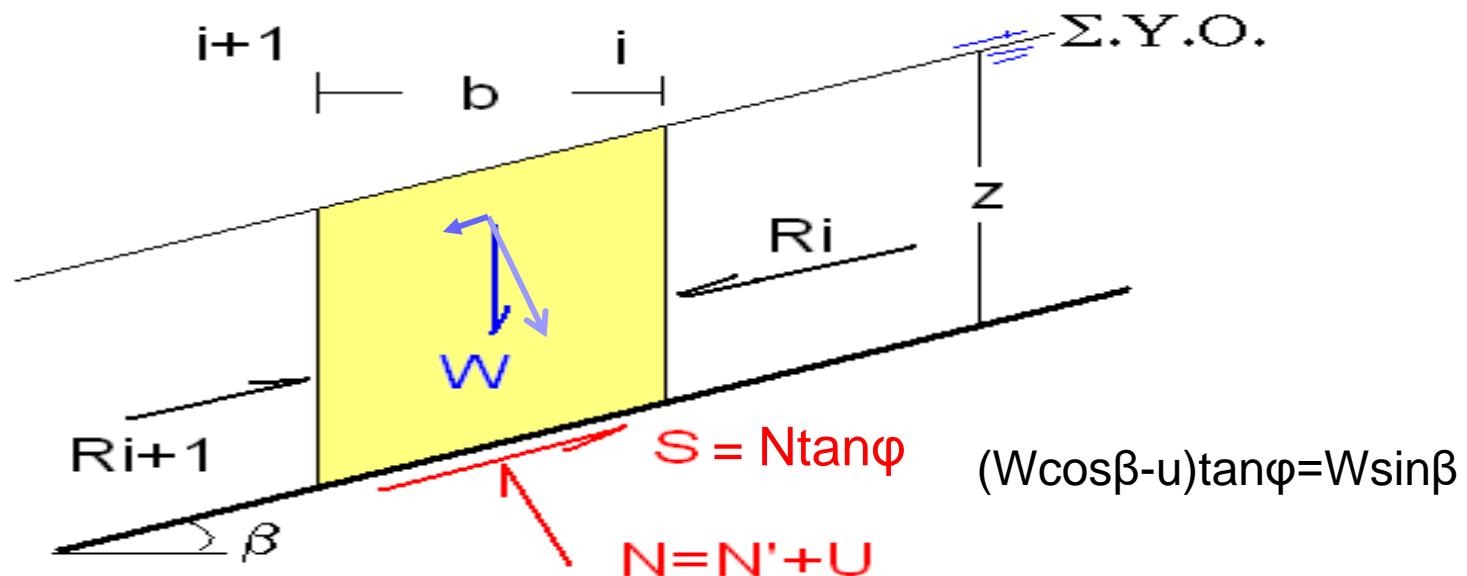
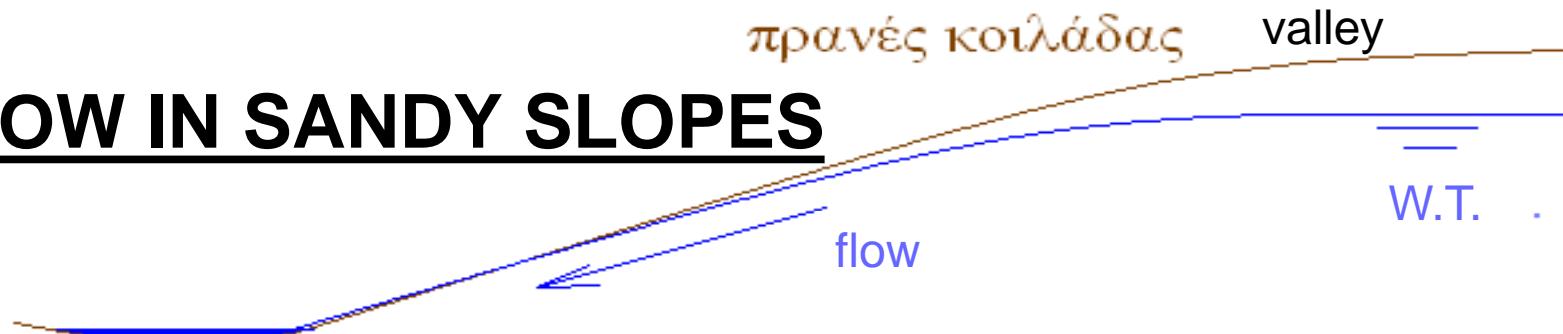
$$Q = N_{\rho} \cdot q_x = -N_{\rho} \cdot k \cdot \frac{-H}{N_{\delta}} \cdot \frac{b_x}{a_x} = k \cdot (h_1 - h_2) \cdot \frac{N_{\rho}}{N_{\delta}}$$

ΑΠΕΙΡΟΜΗΚΕΣ ΠΡΑΝΕΣ ΣΕ ΑΜΜΟ

πρανές κοιλάδας

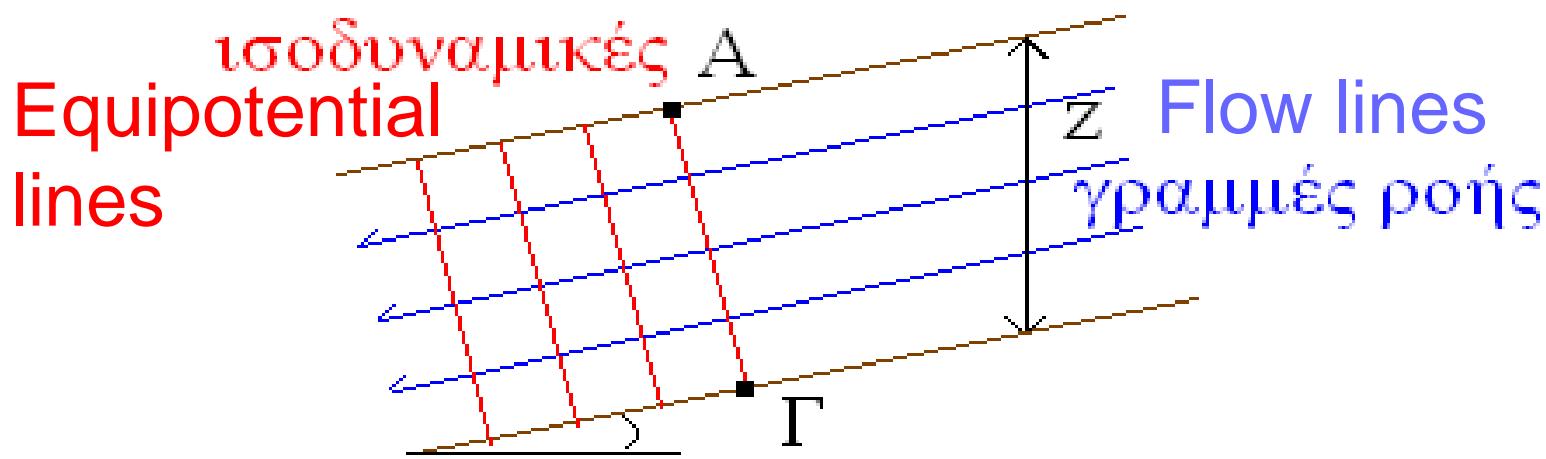
valley

FLOW IN SANDY SLOPES



Flow reduces slope steepness by 50 percent

FLOW IN SLOPES



$$h_A = h_\Gamma = u_A / \gamma_w + z_A = u_\Gamma / \gamma_w + z_\Gamma \rightarrow$$
$$u_\Gamma = (z_A - z_\Gamma) * \gamma_w = A\Gamma * \cos\beta * \gamma_w =$$
$$\gamma_w * \cos^2\beta * z$$

c'=0 & seepage: phreatic line at soil surface

$$u = \gamma_w * z * \cos^2\beta$$

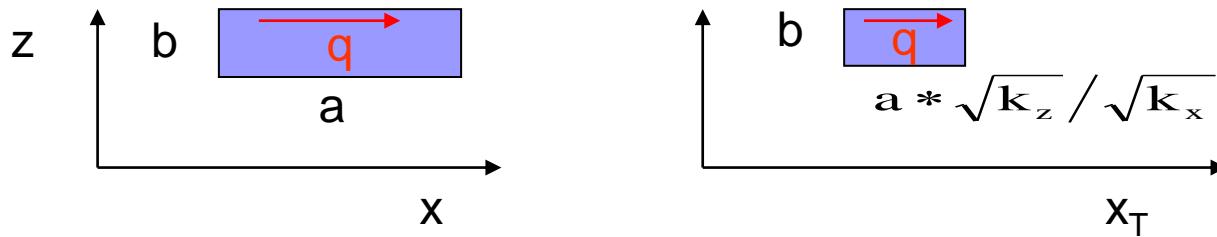
$$(W\cos\beta - \gamma_w\cos^2\beta z)\tan\phi = W\sin\beta \rightarrow [(1 - \gamma_w\cos^2\beta z / (\gamma_z\cos\beta)\cos\beta]\tan\phi = \tan\beta$$

$$(1 - \gamma_w/\gamma)\tan\phi' = \tan\beta \quad (\text{for FS}=1) \rightarrow$$
$$\tan\beta = (\gamma'/\gamma) * \tan\phi' \sim \tan\phi'/2$$

Anisotropic flow conditions

$$\mathbf{k}_z \cdot \frac{\partial^2 \mathbf{h}}{\partial z^2} + \mathbf{k}_x \cdot \frac{\partial^2 \mathbf{h}}{\partial x^2} = \mathbf{0} \rightarrow \frac{\partial^2 \mathbf{h}}{\partial z^2} + \frac{\partial^2 \mathbf{h}}{(\frac{\mathbf{k}_z}{\mathbf{k}_x}) \cdot \partial x^2} = \mathbf{0}$$

$$\frac{\partial^2 \mathbf{h}}{\partial x^2} + \frac{\partial^2 \mathbf{h}}{\partial x_T^2} = \mathbf{0} \xrightarrow{\text{oπον}} \mathbf{x}_T = \left(\frac{\mathbf{k}_z}{\mathbf{k}_x}\right)^{\frac{1}{2}} \cdot \mathbf{x}$$



$$q = -k_x * (\delta h/a) * b * 1 = q = -k' * (\delta h/a) * (\sqrt{k_x}/\sqrt{k_z}) * b * 1 \rightarrow k' = \sqrt{k_x} * \sqrt{k_z}$$

$$\mathbf{Q} = \sqrt{\mathbf{k}_x \cdot \mathbf{k}_z} \cdot (\mathbf{h}_1 - \mathbf{h}_2) \cdot \frac{\mathbf{N}_\rho}{\mathbf{N}_\delta}$$