Algorithmic Game Theory Algorithms for normal-form games and approximate Nash equilibria

Vangelis Markakis markakis@gmail.com

Outline

- Algorithms for finding equilibria in general normal form games
 - The support theorem
 - Analysis of 2x2 and 2xn games
 - Complexity of general nxm games
- Approximate Nash equilibria
 - A subexponential algorithm for any constant ε >0
 - Polynomial time algorithms

Nash equilibria: Existence and computation

- In 0-sum games
 - von Neumann's theorem establishes both existence and an algorithm for finding an equilibrium
 - Boils down to solving one linear program
- In general games?
 - Nash's theorem guarantees only existence
 - Big research question over the last 2 decades

The support of a strategy

- To come up with efficient algorithms, we need to understand better the properties of Nash equilibria
- <u>Definition</u>: For a mixed strategy $\mathbf{p} = (p_1, p_2, ..., p_n)$, the support of \mathbf{p} is the set of pure strategies that have a positive probability of being selected, when we play \mathbf{p}

Supp(**p**) = {i:
$$p_i > 0$$
}

- E.g. if $\mathbf{p} = (2/7, 0, 0, 3/7, 0, 2/7)$, then Supp(\mathbf{p}) = $\{1, 4, 6\}$
 - For pl. 1, Supp(p) shows us which rows have a chance to be selected according to p
 - Respectively, for a strategy of pl. 2, it shows the columns

Utility functions revisited

• Let (p, q) be a strategy profile in a nxm game

-
$$\mathbf{p} = (p_1, p_2,..., p_n), \mathbf{q} = (q_1, q_2,..., q_m)$$

Analyzing the utility function of pl. 1:

$$u_1(\mathbf{p}, \mathbf{q}) = \sum_{i=1}^n \sum_{j=1}^m p_i \cdot q_j \cdot u_1(s_i, t_j) = \sum_{i=1}^n p_i \sum_{j=1}^m q_j \cdot u_1(s_i, t_j) = \sum_{i=1}^n p_i \cdot u_1(e^i, \mathbf{q})$$

The last term can also be written in terms of the support of p, hence:

$$u_1(\mathbf{p}, \mathbf{q}) = \sum_{i \in Supp(\mathbf{p})} p_i \cdot u_1(e^i, \mathbf{q})$$

- Let (p, q) be a Nash equilibrium and let i, j ∈ Supp(p)
 - $p_i > 0, p_i > 0$
- How are the quantities u₁(eⁱ, q) and u₁(e^j, q) related?
- If $u_1(e^i, \mathbf{q}) > u_1(e^j, \mathbf{q})$, then pl. 1 has an incentive to reduce the probability p_i and increase the probability p_i
 - But then (p, q) would not be a Nash equilibrium
 - Similarly, if $u_1(e^i, \mathbf{q}) < u_1(e^j, \mathbf{q})$
 - The only choice at an equilibrium is to have $u_1(e^i, \mathbf{q}) = u_1(e^j, \mathbf{q})$
- If $i \in Supp(\mathbf{p})$ and $j \notin Supp(\mathbf{p})$?
 - Then it must hold that $u_1(e^i, \mathbf{q}) \ge u_1(e^j, \mathbf{q})$, otherwise (\mathbf{p} , \mathbf{q}) is not an equilibrium

Support theorem: A profile (**p**, **q**) is a Nash equilibrium if and only if

- i. $\forall i, j \in Supp(\mathbf{p}), u_1(e^i, \mathbf{q}) = u_1(e^j, \mathbf{q})$
- ii. $\forall i, j \in \text{Supp}(\mathbf{q}), u_2(\mathbf{p}, e^i) = u_2(\mathbf{p}, e^j)$
- iii. $\forall i \in \text{Supp}(\mathbf{p}) \text{ and } \forall j \notin \text{Supp}(\mathbf{p}), u_1(e^i, \mathbf{q}) \ge u_1(e^j, \mathbf{q})$
- iv. $\forall i \in \text{Supp}(\mathbf{q}) \text{ and } \forall j \notin \text{Supp}(\mathbf{q}), u_2(\mathbf{p}, e^i) \geq u_2(\mathbf{p}, e^j)$

In other words:

- If a pure strategy is used with positive probability at a Nash equilibrium, then this strategy should be at least as good as any other pure strategy, given the other player's strategy
- 2 pure strategies that have positive probability at a Nash equilibrium must have the same utility, given the other player's strategy
- The theorem yields a way to check if a profile is a Nash equilibrium
- And helps us understand why some profiles cannot form an equilibrium

Generalizing the support theorem for multi-player games

<u>Theorem:</u> Consider a game with n players. The profile ($\mathbf{p_1}$, $\mathbf{p_2}$, ..., $\mathbf{p_n}$) is a Nash equilibrium if and only if for every player i, it holds that

- i. $\forall j, k \in \text{Supp}(\mathbf{p}_i), u_i(e^j, \mathbf{p}_{-i}) = u_i(e^k, \mathbf{p}_{-i})$
- ii. $\forall j \in \text{Supp}(\mathbf{p}_i)$ και $\forall k \notin \text{Supp}(\mathbf{p}_i)$, $u_i(e^j, \mathbf{p}_{-i}) \geq u_i(e^k, \mathbf{p}_{-i})$

Example

Use the support theorem to check if the profile (\mathbf{p} , \mathbf{q}) with $\mathbf{p} = (3/4, 0, 1/4)$, $\mathbf{q} = (0, 1/3, 2/3)$ is an equilibrium in the following game

	t_1	t_2	t_3
s_1	1, 2	3, 3	1, 1
S ₂	3, 2	0, 1	2, 5
S ₃	2, 4	5, 1	0, 7

Corollary: If we knew the support of the strategies in one equilibrium profile, then we could compute a Nash equilibrium in polynomial time

In other words: if we only knew which rows and columns are needed in an equilibrium, we could then compute the probabilities of the mixed strategies

Proof:

- Suppose that someone guesses the support for both players
- All the conditions of the support theorem are linear functions of p_1 , p_2 ,..., p_n , q_1 , q_2 ,..., q_m
- We would also need to add that Σ_i $p_i = 1$, Σ_i $q_i = 1$
- By solving a single linear program (or a system of linear inequalities)
 we can compute the probabilities of the mixed strategies

- At the end, finding a Nash equilibrium is a combinatorial problem
- It suffices to find the right supports
- Brute-force algorithm:
 - Enumerate all possible pairs of supports for the two players
 - For each pair of supports, check if the corresponding linear program has a solution
- Complexity of brute-force in nxm games: prohibitive!
 - 2ⁿ choices for pl. 1
 - 2^m choices for pl. 2
 - We need to run O(2^{n+m}) linear programs

- Can we reduce it to solving only a few linear programs?
- Or a single LP?
- Probably no...
- Note: If the problem is solvable in polynomial time, then it can be reduced to a 0-sum game, by what we said in previous lecture
- It turns out that finding Nash equilibria is a special case of a "linear complementarity problem" [Cottle, Dantzig, 1960s]

Linear Complementarity Problems (LCP)

- They arise in various contexts in Operations Research
- A class of non-linear programs
- Non-linear constraints for Nash equilibria:
 - By the support theorem, we need to express the fact that if p_i > 0 at an equilibrium, then the i-th pure strategy gives maximum payoff among all pure strategies
- We cannot express such "if" statements with a linear program
- Instead: let w be the expected payoff of pl. 1 at an equilibrium
 (p, q)
- Support theorem \Rightarrow if $p_i > 0$, then $u_1(e^i, \mathbf{q}) = w$
- Equivalently: $p_i \cdot (u_1(e^i, \mathbf{q}) w) = 0$ [complementarity condition]

Nash equilibria as a LCP

Variables:

- $-p_1, p_2, ..., p_n, q_1, q_2, ..., q_m$: for the probabilities of the mixed strategies
- w, w': for the expected utilities of the 2 players

Constraints:

- $-\Sigma_i p_i = 1, \Sigma_i q_i = 1$
- $p_1 \ge 0, p_2 \ge 0, ..., q_1 \ge 0, ..., q_m \ge 0$
- w ≥ $u_1(e^i, q)$ for i=1,..., n
- w' ≥ $u_2(\mathbf{p}, e^j)$ for j=1,..., m
- $p_i \cdot (u_1(e^i, \mathbf{q}) w) = 0$, for i=1,..., n
- $q_i \cdot (u_2(\mathbf{p}, e^j) w') = 0$, for j=1,..., m
- Algorithm for solving LCPs: [Lemke, Howson '64]
 - Exponential time in worst case, but relatively ok on average
 - Based on ideas similar to simplex but for non-linear problems
 - see GAMBIT http://www.gambit-project.org/

- So far, we have only seen exponential time algorithms...
- In what cases can the support theorem help us in having better algorithms?
- 2x2 games:
 - If there is a mixed strategy equilibrium then the support for pl. 1 must contain both rows
 - The support of pl. 2 must contain both columns
 - Applying the support theorem, it must hold that

$$u_1(e^1, \mathbf{q}) = u_1(e^2, \mathbf{q}), \text{ and } u_2(\mathbf{p}, e^1) = u_2(\mathbf{p}, e^2)$$

Applying the support theorem to Bach-or-Stravinsky (BoS)

	B	S
B	2, 1	0, 0
S	0, 0	1, 2

If there exists a Nash equilibrium with mixed strategies, in the form ((p_1 , 1- p_1), (q_1 , 1- q_1)), with p_1 , $q_1 \in (0, 1)$, it should hold that

- $2q_1 = 1 q_1 \Rightarrow q_1 = 1/3$
- $p_1 = 2(1-p_1) \Rightarrow p_1 = 2/3$
- The conditions for pl. 1 give us the mixed strategy of pl. 2
- Similarly the conditions for pl. 2 give the strategy of pl. 1
- Hence we have the mixed equilibrium ((2/3, 1/3), (1/3, 2/3))

From 2x2 to 2xn games

	t ₁	t ₂	t ₃	t ₄
S ₁	3, -2	1, 2	4, 6	2, 8
s ₂	1, 12	5, 10	2, 4	3, -4

- What are the Nash equilibria in this game?
- There is no Nash equilibrium with pure strategies, hence, there must be one with mixed strategies
- We will start with pl. 1
 - i.e., with the player who has 2 pure strategies
- We are looking for a strategy $\mathbf{p} = (p_1, p_2) = (p_1, 1 p_1)$ of pl. 1

	t_1	t_2	t_3	t ₄
S ₁	3, -2	1, 2	4, 6	2, 8
S ₂	1, 12	5, 10	2, 4	3, -4

Step 1: We look at pl. 2 and compute the terms

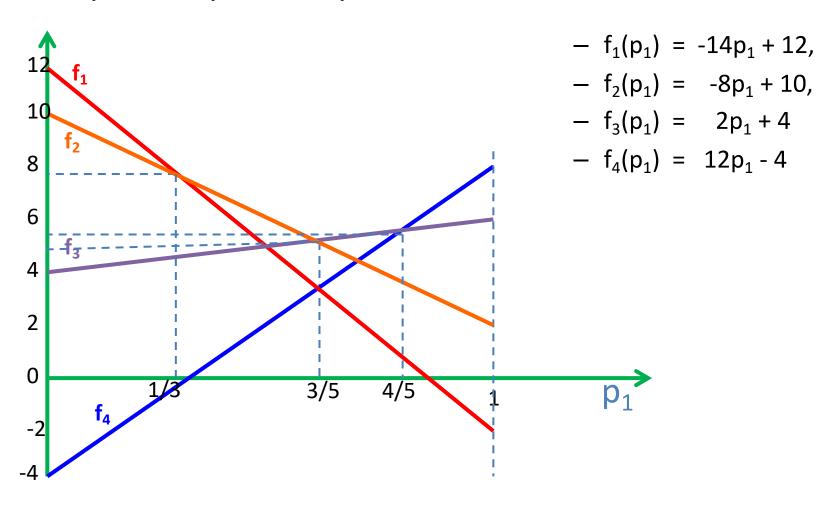
$$- u_2(\mathbf{p}, e^1) = f_1(p_1) = -14p_1 + 12,$$

$$- u_2(\mathbf{p}, e^2) = f_2(\mathbf{p}_1) = -8\mathbf{p}_1 + 10,$$

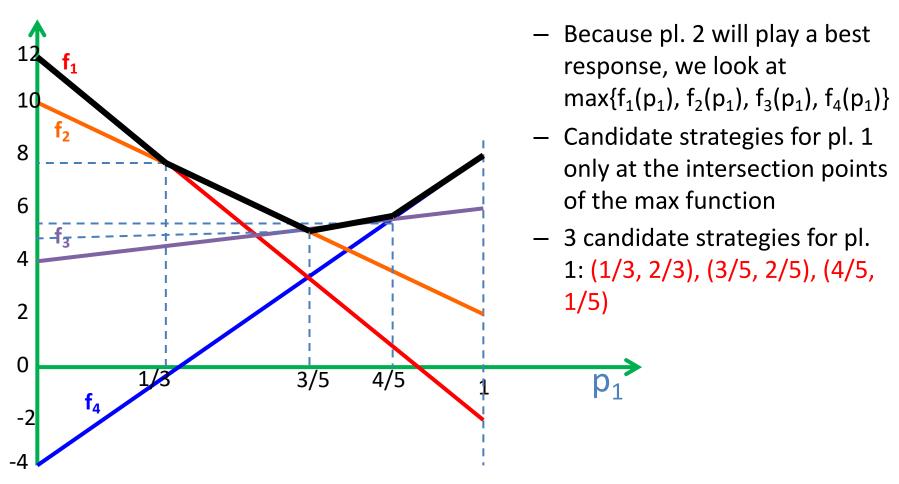
$$- u_2(\mathbf{p}, e^3) = f_3(\mathbf{p}_1) = 2\mathbf{p}_1 + 4$$

$$- u_2(\mathbf{p}, e^4) = f_4(\mathbf{p}_1) = 12\mathbf{p}_1 - 4$$

Step 2: Graphical representation



Step 3: Candidate strategies for pl. 1



	t_1	t_2	t_3	t ₄
s ₁	3, -2	1, 2	4, 6	2, 8
s ₂	1, 12	5, 10	2, 4	3, -4

 Step 4: We check all the candidate strategies to see if they can yield an equilibrium

1st candidate strategy of pl. 1: (1/3, 2/3)

- We will search for a strategy of pl. 2 in the form: $\mathbf{q} = (q_1, 1 q_1, 0, 0)$
- Since from the diagram, the 1st and 2nd columns are the best responses of pl. 2 to the strategy of pl. 1
- From the support theorem, it must hold that $u_1(e^1, \mathbf{q}) = u_1(e^2, \mathbf{q})$
- $-3q_1 + 1-q_1 = q_1 + 5(1-q_1) \Rightarrow q_1 = 2/3$
- Since we found a valid probability, we have found a Nash equilibrium

	t_1	t_2	t_3	t ₄
s ₁	3, -2	1, 2	4, 6	2, 8
s ₂	1, 12	5, 10	2, 4	3, -4

 Step 4: We check all the candidate strategies to see if they can yield an equilibrium

2nd candidate strategy of pl. 1: (3/5, 2/5)

- We will search for a strategy of pl. 2 in the form: $\mathbf{q} = (0, q_2, 1 q_2, 0)$
- Since from the diagram, the 2nd and 3rd columns are the best responses against the strategy of pl. 1
- From the support theorem, it should hold that $u_1(e^2, \mathbf{q}) = u_1(e^3, \mathbf{q})$
- By solving this, we get $q_2 = 1/3$
- Since we found a valid probability, we have found one more equilibrium³

 Step 4: We check all the candidate strategies to see if they can yield an equilibrium

3rd candidate strategy of pl. 1: (4/5, 1/5)

- We will search for a strategy of pl. 2 of the form: $\mathbf{q} = (0, 0, q_3, 1 q_3)$
- In a similar way, we get $q_3 = 1/3$
- Hence we have a 3rd Nash equilibrium

	t_1	t_2	t_3	t ₄
S ₁	3, -2	1, 2	4, 6	2, 8
S ₂	1, 12	5, 10	2, 4	3, -4

- In total: 3 Nash equilibria
 - -((1/3, 2/3), (2/3, 1/3, 0, 0))
 - -((3/5, 2/5), (0, 1/3, 2/3, 0))
 - -((4/5, 1/5), (0, 0, 1/3, 2/3,))

	t_1	t_2	t_3	t_4
s ₁	3, -2	5 , 2	4, 6	2, 8
s ₂	1, 12	1 , 10	2, 4	3, -4

- Suppose we change some of the payoffs of pl. 1 (here we changed the 2nd column)
- Which parts of the analysis change?
 - Observation: The candidate mixed strategies of pl. 1 were determined by the payoff matrix of pl. 2!
 - Hence, steps 1-3 remain exactly the same
 - Again, 3 candidate strategies for pl. 1

	t_1	t_2	t_3	t ₄
S ₁	3, -2	5 , 2	4, 6	2, 8
S ₂	1, 12	1, 10	2, 4	3, -4

 Step 4: We check all the candidate strategies to see if they can yield an equilibrium

1st candidate strategy of pl. 1: (1/3, 2/3)

- We will search for a strategy of pl. 2 in the form: $\mathbf{q} = (q_1, 1 q_1, 0, 0)$
- From the support theorem, it must hold that $u_1(e^1, \mathbf{q}) = u_1(e^2, \mathbf{q})$
- $-3q_1 + 5(1-q_1) = q_1 + 1-q_1 \Rightarrow q_1 = 2$
- Not a valid probability!
- Hence, this candidate strategy does not yield an equilibrium

	t_1	t_2	t_3	t ₄
S_1	3, -2	5 , 2	4, 6	2, 8
S ₂	1, 12	1 , 10	2, 4	3, -4

 Step 4: We check all the candidate strategies to see if they can yield an equilibrium

2nd candidate strategy of pl. 1: (3/5, 2/5)

- We will search for a strategy of pl. 2 in the form : $\mathbf{q} = (0, q_2, 1 q_2, 0)$
- From the support theorem, it should hold that $u_1(e^2, \mathbf{q}) = u_1(e^3, \mathbf{q})$
- $5q_2 + 4(1-q_2) = q_2 + 2(1-q_2) \Rightarrow q_2 = -1$
- Not a valid probability
- Hence, no equilibrium

	t_1	t_2	t_3	t ₄
S ₁	3, -2	5 , 2	4, 6	2, 8
S ₂	1, 12	1 , 10	2, 4	3, -4

 Step 4: We check all the candidate strategies to see if they can yield an equilibrium

3rd candidate strategy of pl. 1: (4/5, 1/5)

- Since we have not found any other equilibrium, Nash's theorem guarantees that now we will find one
- We will search for a strategy of pl. 2 of the form: $\mathbf{q} = (0, 0, q_3, 1 q_3)$
- In the modified example, columns 3 and 4 have not changed
- Hence, we will arrive at the same result: $q_3 = 1/3$
- Unique Nash equilibrium: ((4/5, 1/5), (0, 0, 1/3, 2/3,))

Back to nxm games

- Summarizing known algorithms:
 - Brute-force, based on the support theorem, worst case: need to solve $O(2^{n+m})$ linear programs
 - [Lemke, Howson '64], worst case: still exponential
 - Other approaches: [Kuhn '61, Mangasarian '64, Lemke '65], also exponential worst case running time
- Polynomial time algorithms only for special cases
 - 0-sum games
 - 2xn games
 - Games with constant rank payoff matrices
- We are not aware of any polynomial time algorithm for general nxm normal form games!

Algorithms for normal form games

- Could it be that the problem is NP-complete?
- Probably not
 - [Megiddo, Papadimitriou '89]: strong evidence that it cannot be NP-complete
 - If it were \Rightarrow **NP** = co-**NP** (highly unlikely to be true)
- It is **NP**-complete if we add more requirements
 - E.g. Find a Nash equilibrium that maximizes the sum of the utilities
 [Gilboa, Zemel '89, Conitzer, Sandholm '03]
 - A different problem than just finding a Nash equilibrium
- Further issues
 - There exist games, with integer payoff matrices, and with ≥ 3 players, where the probabilities in their Nash equilibria are irrational numbers [Nash '51]
 - Hence, we cannot even represent the mixed strategies by a finite number of bits

Back to the proof of Nash's theorem

- Theorem [Nash 1951]: Every finite game possesses at least one equilibrium when we allow mixed strategies
- Nash's proof reduces to using Brouwer's fixed point theorem
- Brouwer's theorem reduces to using Sperner's lemma

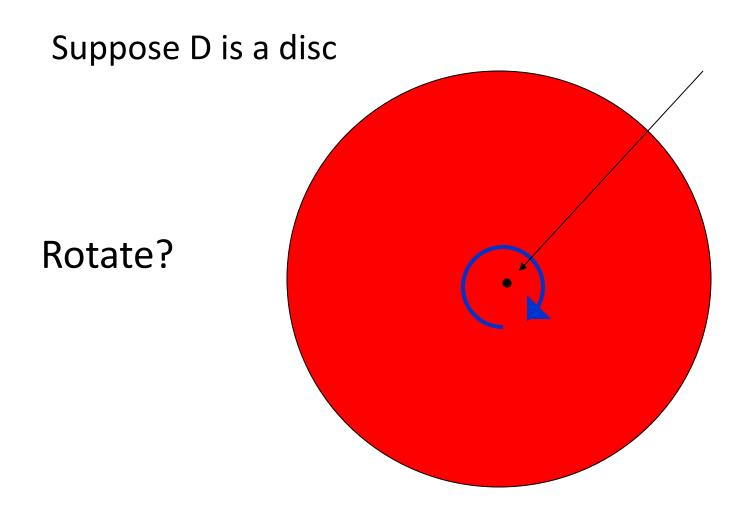
Brouwer's theorem

Brouwer's theorem: Let f:D→D, be a continuous function, and suppose D is convex and compact.
 Then there exists x such that f(x) = x

Illustrations of Brouwer's theorem

Suppose D is a disc Flip?

Illustrations of Brouwer's theorem



Sperner's lemma

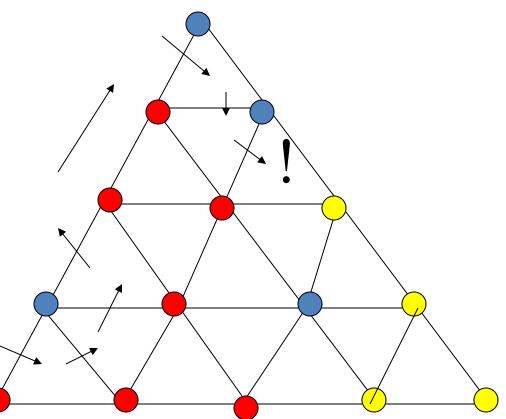
In 2 dimensions

- Let D be the 2-dimensional simplex
 - D = { (x_1, x_2, x_3) : $x_1 + x_2 + x_3 = 1$, $x_i \ge 0$, for i=1, 2, 3 }
 - D is a triangle
- Consider a triangulation of D
- Color all the vertices of the small triangles, using 3 colors such that:
 - The 3 vertices of D have a different color
 - Along each edge of D, we use only the colors of the 2 vertices of the edge (1 color forbidden)
 - No restriction for the interior of D

Sperner's lemma

Sperner's

Lemma: Any such coloring has at least one trichromatic triangle



Algorithms for normal form games

Let us look at the computational problems:

- SPERNER: Given a coloring satisfying the conditions of Sperner's lemma, find a trichromatic triangle
- BROUWER: Given a function satisfying the conditions of Brouwer's theorem, find a fixed point
- NASH: Given a finite normal form game, find a Nash equilibrium

What is common with all 3?

They are search problems, where we know a solution always exists

Complexity classes for search problems

Informal descriptions

- FP (Function P): The version of P for search problems
- FNP (Function NP): The version of NP for search problems
- TFNP (Total FNP): The class of search problems that always have a solution

Fact: $FP \subseteq TFNP \subseteq FNP$

Complexity classes for search problems

- TFNP has several interesting subclasses
- Depending on how the proof of existence is established
- PLS (Polynomial time Local Search)
- PPA (Polynomial time Parity Argument)
- PPAD (Polynomial time Parity Argument, Directed)
- PPP (Polynomial time Pigeonhole Principle)
- And more...

In fact, our problems belong to one of these subclasses

The class PPAD

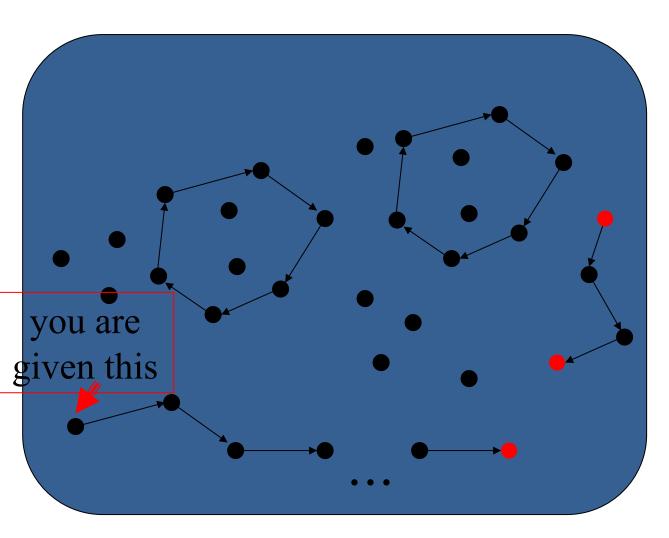
[Papadimitriou '94]

- Consists of problems where the existence of a solution can be established by a particular kind of parity argument
- ➤ Namely, PPAD contains all problems that can be reduced to:

END OF THE LINE:

- We are given a directed graph with in-degree(u), out-degree(u) ≤ 1 for every vertex u
- The graph is given implicitly by two circuits P, C
 - (u,v) is an edge iff u = P(v) and v = C(u)
 - i.e., we are only allowed to ask queries for the successor or the predecessor of a node (at most polynomially many queries)
- We are also given a source node (in-degree=0)
- Goal: Find the sink, or another source
 - existence of such a node is guaranteed, by a parity argument: the total number of sources and sinks is even

The class PPAD



Q: Is there an efficient algorithm for finding another unbalanced node without actually following the path?

Complexity of finding a Nash equilibrium

- Open problem for many years
- Eventually:
 - The problem belongs to PPAD
 - Membership in PPAD is established via the Lemke-Howson algorithm
 - [Daskalakis, Goldberg, Papadimitriou, September 2005]: PPAD-complete for 4-player games, conjectured that for 2 players there is an efficient algorithm
 - [Chen, Deng, November 2005]: PPAD-complete even for 2-player games!
 - [Chen, Deng, Teng, February 2006]: PPAD-complete even for some approximate versions of equilibria
 - Current belief is that problems in PPAD are not poly-time solvable
 - Finding an exact Nash equilibrium is most probably intractable

Other PPAD-complete problems

How can we define **BROUWER** as a computational problem?

- Consider a function f that satisfies the conditions of Brouwer's theorem
 - It may not be easy to succinctly describe f as input to the algorithm
 - Also, the fixed point may contain irrational numbers
- Thus, the function is given implicitly via a circuit (only allowed to ask queries for the value of the function at any point of the domain)
- Goal: Find an approximate fixed point: a point x such that $|f(x) x| < \epsilon$

Theorem: BROUWER is PPAD-complete

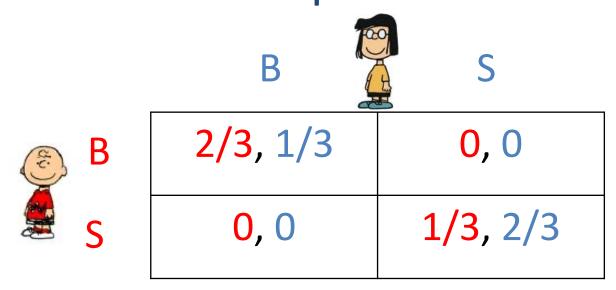
Finding a Nash equilibrium is equivalent to finding approximate fixed points of continuous functions

 Note that the proof of Nash's theorem only showed that finding an equilibrium is at most as difficult as finding fixed points

- Since the problem of computing equilibria is hard, we can consider possible relaxations of the initial definition
- Recall the definition of Nash equilibria: A profile of mixed strategies (p, q) is a Nash equilibrium if
 - $u_1(\mathbf{p}, \mathbf{q}) \ge u_1(\mathbf{e}^i, \mathbf{q})$ for every pure strategy \mathbf{e}^i of pl. 1
 - $u_2(\mathbf{p}, \mathbf{q}) \ge u_2(\mathbf{p}, \mathbf{e}^{\mathbf{j}})$ for every pure strategy $\mathbf{e}^{\mathbf{j}}$ of pl. 2

- <u>Definition</u>: A profile of mixed strategies (p, q) is an ε-Nash equilibrium if
 - $u_1(\mathbf{p}, \mathbf{q}) \ge u_1(\mathbf{e}^i, \mathbf{q}) \varepsilon$, for every pure strategy \mathbf{e}^i of pl. 1
 - $-u_2(\mathbf{p}, \mathbf{q}) \ge u_2(\mathbf{p}, \mathbf{e}^{\mathbf{j}}) \varepsilon$, for every pure strategy $\mathbf{e}^{\mathbf{j}}$ of pl. 2
- In words: a profile of strategies is an ε -Nash equilibrium if no player can gain more than ε by deviating
- When we study ϵ -Nash equilibria, we usually normalize the utilities to be in [0, 1]
 - − Thus also ε ∈ [0, 1]

Example of approximate Nash equilibria



Consider the profile (p, q) = ((0.6, 0.4), (0.4, 0.6))

- $u_1(p, q) = 0.6 \times 0.4 \times 2/3 + 0.4 \times 0.6 \times 1/3 = 0.24$
- $u_1(e^1, q) = 0.4 \times 2/3 = 0.267 = u_1(p, q) + 0.027$
- $u_1(e^2, q) = 0.6 \times 1/3 = 0.2 < 0.24$
- Similar analysis for pl. 2
- Hence, this profile is a 0.027-Nash equilibrium

None of the players can gain more than 0.027 by deviating to another strategy

A stronger notion of approximation

- In words: a profile of strategies (**p**, **q**) is an ε-well-supported Nash equilibrium if any strategy from Supp(**p**) is an approximate best response to **q** and vice versa
- Formally: (**p**, **q**) is an ε-well-supported Nash equilibrium if:
 - $u_1(e^i, q) \ge u_1(e^k, q) \varepsilon$, for every $i \in \text{Supp}(p)$ and every $k \in \{1, 2, ..., n\}$
 - $u_2(\mathbf{p}, e^j) \ge u_2(\mathbf{p}, e^k) \varepsilon$, for every $i \in \text{Supp}(\mathbf{q})$ and every $k \in \{1, 2, ..., n\}$

Fact: An ε-well-supported Nash equilibrium is also an ε-Nash equilibrium (but not vice versa)

Searching for Approximate Equilibria

- We will focus on the simpler version of ε-Nash equilibria
- At the same time, we also want to focus on strategy profiles that are simple, and easy to describe

Definition: A *k*-uniform strategy is a strategy where all probabilities are integer multiples of 1/*k* e.g. (3/*k*, 0, 0, 1/*k*, 5/*k*, 0,..., 6/*k*)

Important observation: Support size of a k-uniform strategy ≤ k

Can we have approximate equilibria with k-uniform strategies for small values of k?

A Subexponential Algorithm (Quasi-PTAS)

Theorem [Lipton, Markakis, Mehta '03]: Consider a nxn game. For any ε in (0,1), and for every $k \ge 9logn/\varepsilon^2$, there exists a pair of k-uniform strategies (\mathbf{p} , \mathbf{q}) that forms an ε -Nash equilibrium

Lesson learnt: there is no need to use a big support!

For 0-sum games already proved in [Althofer '94, Lipton, Young '94]

Proof idea:

- Use of the "Probabilistic Method"
- Sample a mixed strategy for each player according to the distribution of a Nash equilibrium
 - Feasible because of Nash's theorem
- Then prove that with positive probability the desired property holds

A Subexponential Algorithm (Quasi-PTAS)

Theorem [Lipton, Markakis, Mehta '03]: Consider a nxn game. For any ε in (0,1), and for every $k \ge 9logn/\varepsilon^2$, there exists a pair of k-uniform strategies (\mathbf{p} , \mathbf{q}) that forms an ε -Nash equilibrium

Corollary : We can compute an ε -Nash equilibrium in time

$$n^{O(\log n/\epsilon^2)}$$

Proof of Corollary: There are $n^{O(k)}$ pairs of supports to look at. Verify the ε -equilibrium condition.

Generalizations

- The same property holds for ε-well-supported equilibria as well [Kontogiannis, Spirakis '10]
- For m-player games with n pure strategies per player, the same technique yields an algorithm for approximate Nash equilibria with
 - support size: $k = O(m^2 \log(m^2 n)/\varepsilon^2)$
 - running time: exponential in logn, m, $1/\varepsilon$
- Previously known approximations:
 - [Scarf '67]: exponential in n, m, $log(1/\varepsilon)$) (via fixed point approximations)

An application

[McCarthy, Laan, Wang, Vayanos, Sinha, Tambe '18]

- Threat Screening Games: Games for modeling decision problems related to screening at airports, borders, and other areas
- Motivated by a collaboration with the US Transportation Security Administration
- Use of mixed strategies for selecting how to screen quite popular during last years
- Main practical result: Simulations for screening in a large airport (comparable to the Los Angeles International Airport) show that approximate equilibria with k-uniform small support strategies behave very well and have the potential to be deployed in practice

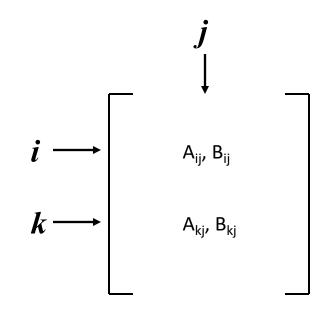
Moving on...

- How good is an algorithm with running time n^{O(logn/ε^2)}?
- For sure better than exponential
 - Better than nⁿ or 2ⁿ
- But still not polynomial running time
 - Usually referred to as quasi-polynomial
- For what values of ϵ can we have polynomial time algorithms?

Polynomial Time Approximation Algorithms

For
$$\varepsilon = 1/2$$
:

- Pick arbitrary row i
- Let j = BR(i) = best response to i
- Find k = BR(j), pl. 1 plays i or k with prob. 1/2 each
- Pl. 2 just plays j



Proposition: This is a 1/2-approximate equilibrium with support size ≤ 2 for both players!

[Feder, Nazerzadeh, Saberi '07]: For ε < 1/2, we need in worst case, support at least $\Omega(\log n)$

Polynomial Time Approximation Algorithms

Better than ½-approximations in polynomial time

```
[Daskalakis, Mehta, Papadimitriou '07]: polynomial time algorithm for \varepsilon = 1-1/\varphi = (3-\sqrt{5})/2 \approx 0.382 (\varphi = golden ratio)
```

- Based on sampling + Linear Programming
- Need to solve polynomial number of linear programs
- Not a very fast algorithm
- Polynomial time algorithm but still a large number of linear programs to be solved

Polynomial Time Approximation Algorithms

[Bosse, Byrka, Markakis '07]: a different LP-based method with the same approximation of 0.382

- Needs to solve only 1 linear program
- Similar idea in [Kontogiannis, Spirakis '07] for wellsupported approximation
- A small tweak can also yield a better approximation of 0.36

Recall: 0-sum games can be solved in polynomial time (equivalent to linear programming)



- Given a game defined by the arrays (A, B), start with an equilibrium of the 0-sum game (A-B, B-A)
- If incentives to deviate are "high", players adjust their strategies via best response moves

A 0.382-approximation algorithm

Parameters of the algorithm: α , $\delta_2 \in [0,1]$

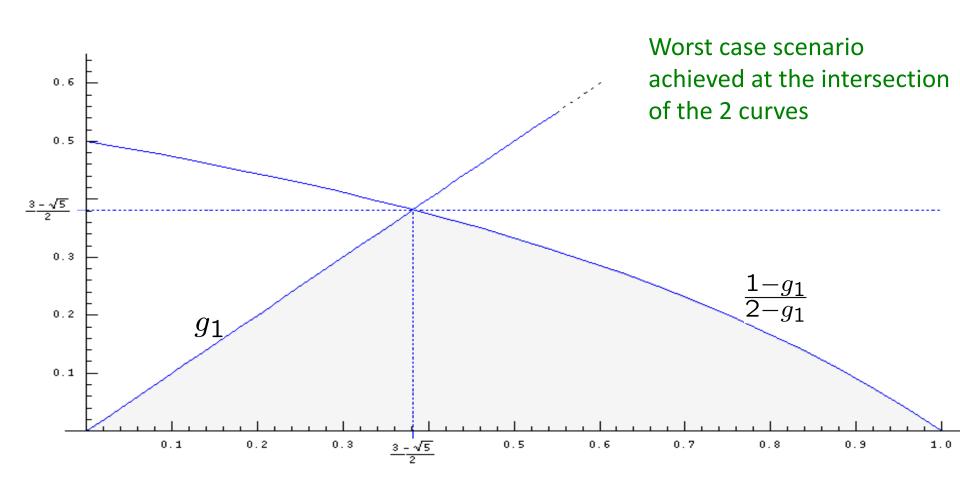
- 1. Find an equilibrium x^* , y^* of the 0-sum game (A B, B A)
- 2. Let g_1 , g_2 be the maximum gain by deviating to a pure strategy for row and column player. Suppose $g_1 \ge g_2$
- 3. If $g_1 \leq \alpha$, output x^* , y^*
- 4. Else: let b_1 = best response to y^* , b_2 = best response to b_1
- 5. Output:

$$x = b_1$$

 $y = (1 - \delta_2) y^* + \delta_2 b_2$

Theorem: The algorithm with $\alpha = 1-1/\varphi$ and $\delta_2 = (1-g_1)/(2-g_1)$ achieves a $(1-1/\varphi)$ -approximation

A 0.382-approximation algorithm



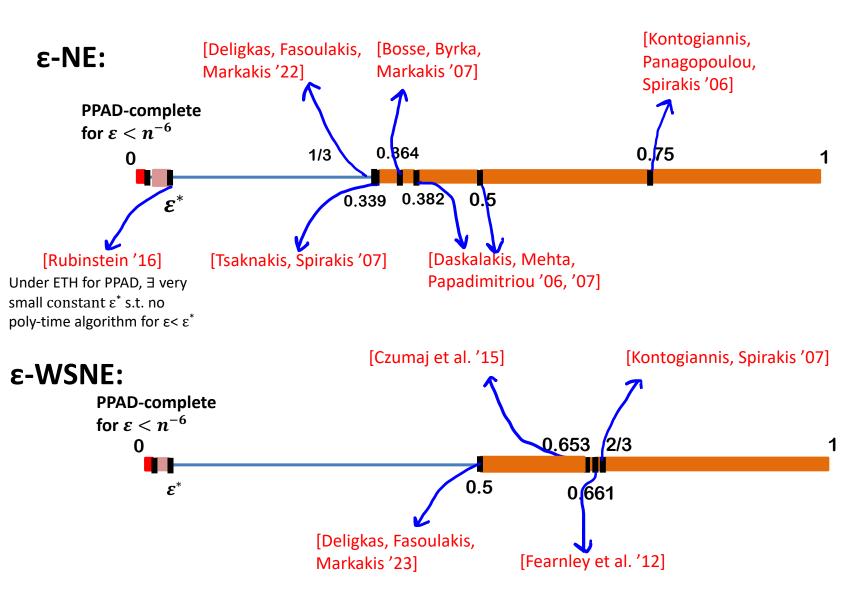
Yet another approach

- [Spirakis, Tsaknakis '07]: algorithm with an approximation of $\varepsilon = 0.339$
 - Best known approximation for many years, till recently
 - A different optimization approach, but yet another LP-based method
 - It starts with a descent-based method to identify a stationary point
 - Needs to solve a polynomial number of linear programs (one per each iteration)
- [Deligkas, Fasoulakis, Markakis '22]: Currently best approximation of $\varepsilon = 1/3$
 - Based on a tweak of the Spirakis-Tsaknakis algorithm
 - Improving the bottleneck case of their algorithm
- Big open problem:
 - Can we find algorithms for lower values of ε , closer to 0?
 - Is it possible to have a poly-time algorithm for any constant ε >0?
 - Probably not... [Rubinstein '16]
- So far, there have been further improvements for several special classes of games
 - Low-rank matrices, sparse matrices, symmetric games, win-lose games, ...

Progress on other notions of approximation

- ε-well-supported equilibria:
 - [Kontogiannis, Spirakis '10]: Polynomial time only for $\varepsilon = 2/3$, based also on solving 0-sum games
 - More recently improved to 0.6528 [Czumaj et al. '18]
 - And even more recently improved to ½ [Deligkas, Fasoulakis, Markakis '23]
- Even stronger notion of approximation: require that the profile found is geometrically close to an exact Nash equilibrium
 - [Etessami, Yannakakis '07]: mostly negative results
- Open problem to provide more positive results, even for special cases, for these concepts as well

The story so far for ε -NE and ε -WSNE



Post-Mortem

- Difficult to find exact Nash equilibria for an arbitrary 2-player game
- A bit less difficult to find approximate Nash equilibria
 - But still challenging and not yet well understood
- Is it a catastrophe if we do not have efficient algorithms for every game?
 - Players in practice may also be able to adjust their strategies and gradually converge to an equilibrium by observing each other's actions
 - Still, "if your laptop cannot find an equilibrium, then neither can the market", quote from Kamal Jain (2003)
- Despite the high complexity, the notion of a Nash equilibrium remains among the most important notions in game theory

Post-Mortem

- Take-home story: Nash equilibria form a good starting point from a conceptual point of view
- But when intractable, we should think towards alternative and tractable variations of equilibrium concepts
- Ongoing research:
 - Learning algorithms with convergence guarantees
 - Also connected to training neural networks
 - Many positive results for 0-sum games (starting with fictitious play [Robinson '51])
 - Not as easy for general games
 - No-regret algorithms provide convergence "on average"
 - Several variations of gradient descent under consideration during last 5 years...