## The Infinite Case: Rademacher Complexity and VC-dimension



$$m_{\mathcal{H}}(\epsilon, \delta) \le m_{\mathcal{H}}^{\scriptscriptstyle UC}(\epsilon/2, \delta) \le \left\lceil \frac{2\log(2|\mathcal{H}|/\delta)}{\epsilon^2} \right\rceil$$

Is it still possible to learn if |H| is infinite?

Είναι άραγε τόσο δύσκολο, ακόμα και για πολύ απλούς ταξινομητές όπως οι axis-aligned rectangles (που όμως έχει άπειρο |Η|), να βρούμε ένα άνω φράγμα για το σφάλμα της γενίκευσης;



OXI: έχουμε φράγματα για το σφάλμα της γενίκευσης και στην περίπτωση της απειρομελούς κλάσης υποθέσεων:

φράγμα Rademacher <= Growth <= VC-dimension (shattering dimension)

Nothing new ...

- Samples *S* = ((*x*<sub>1</sub>, *y*<sub>1</sub>), ..., (*x<sub>m</sub>*, *y<sub>m</sub>*))
- Labels  $y_i = \{-1, +1\}$
- Hypothesis  $h: X \rightarrow \{-1, +1\}$
- Training error:  $\hat{R}(h) = \frac{1}{m} \sum_{i}^{m} \mathbb{1}[h(x_i) \neq y_i]$

$$\hat{R}(h) = \frac{1}{m} \sum_{i}^{m} \mathbb{1}\left[h(x_i) \neq y_i\right]$$
(1)

(2)

(3)

(4)

$$\hat{R}(h) = \frac{1}{m} \sum_{i}^{m} \mathbb{1} [h(x_i) \neq y_i]$$

$$= \frac{1}{m} \sum_{i}^{m} \begin{cases} 1 & \text{if } (h(x_i, y_i) == (1, -1) \text{ or } (-1, 1) \\ 0 & (h(x_i, y_i) == (1, 1) \text{ or } (-1, -1) \end{cases}$$
(2)

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$$(1)$$

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(1)
(2)
(3)
(4)

Correlation between predictions and labels

$$\hat{R}(h) = \frac{1}{m} \sum_{i}^{m} \mathbb{1} [h(x_i) \neq y_i]$$

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$$= \frac{1}{2} - \frac{1}{2m} \sum_{i}^{m} y_i h(x_i)$$
(1)
(2)
(3)
(4)

Minimizing training error is thus equivalent to maximizing correlation

$$\arg\max_{h} \frac{1}{m} \sum_{i}^{m} y_{i} h(x_{i})$$
(5)

$$\sigma_{i} = \begin{cases} +1 & \text{with prob .5} \\ -1 & \text{with prob .5} \end{cases}$$
(6)

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This gives us Rademacher correlation—what's the best that a random classifier could do?

$$\hat{\mathscr{R}}_{S}(H) \equiv \mathbb{E}_{\sigma} \left[ \max_{h \in H} \frac{1}{m} \sum_{i}^{m} \sigma_{i} h(x_{i}) \right]$$
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(7)

Notation:  $\mathbb{E}_{\rho}[f] \equiv \sum_{x} \rho(x) f(x)$ 

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(7)

Note: Empirical Rademacher complexity is with respect to a sample.

$$|H| = 1$$

$$|H| = 2^m$$

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$$|H| = 2^{m}$$

$$|H| = 1$$
  
$$h(x_i) \mathbb{E}_{\sigma} \left[ \frac{1}{m} \sum_{i}^{m} \sigma_i \right]$$

$$|H| = 2^{m}$$

$$|H| = 1$$
  
$$h(x_i)\mathbb{E}_{\sigma}\left[\frac{1}{m}\sum_{i}^{m}\sigma_i\right] = 0$$

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$$\frac{m}{m} = 1$$

- Rademacher correlation is larger for more complicated hypothesis space.
- What if you're right for stupid reasons?

We can generalize Rademacher complexity to consider all sets of a particular size.

$$\mathscr{R}_{m}(H) = \mathbb{E}_{S \sim D^{m}} \left[ \hat{\mathscr{R}}_{S}(H) \right]$$
(8)

#### Theorem

**Convergence Bounds** Let *F* be a family of functions mapping from *Z* to [0, 1], and let sample  $S = (z_1, ..., z_m)$  were  $z_i \sim D$  for some distribution *D* over *Z*. Define  $\mathbb{E}[f] \equiv \mathbb{E}_{z \sim D}[f(z)]$  and  $\hat{\mathbb{E}}_S[f] \equiv \frac{1}{m} \sum_{i=1}^m f(z_i)$ . With probability greater than  $1 - \delta$  for all  $f \in F$ :

$$\mathbb{E}[f] \le \hat{\mathbb{E}}_{s}[f] + 2\mathcal{R}_{m}(F) + \mathcal{O}\left(\sqrt{\frac{\ln \frac{1}{\delta}}{m}}\right)$$
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(8)

f is a surrogate for the accuracy of a hypothesis (mathematically convenient)

Aside: McDiarmid's Inequality

If we have a function:

$$|f(x_1,\ldots,x_i,\ldots,x_m)-f(x_1,\ldots,x_i',\ldots,x_m)| \le c_i$$
(9)

then:

$$\Pr[f(x_1,\ldots,x_m) \ge \mathbb{E}\left[f(X_1,\ldots,X_m)\right] + \epsilon] \le \exp\left\{\frac{-2\epsilon^2}{\sum_i^m c_i^2}\right\}$$
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Proof in Mohri (appendix D.7, p.442) (requires Martingale, constructing  $V_k = \mathbb{E} [V | x_1 \dots x_k] - \mathbb{E} [V | x_1 \dots x_{k-1}]$ ).

**Theorem D.8 (McDiarmid's inequality)** Let  $X_1, \ldots, X_m \in \mathfrak{X}^m$  be a set of  $m \ge 1$  independent random variables and assume that there exist  $c_1, \ldots, c_m > 0$  such that  $f: \mathfrak{X}^m \to \mathbb{R}$  satisfies the following conditions:

$$\left|f(x_1,\ldots,x_i,\ldots,x_m) - f(x_1,\ldots,x'_i,\ldots,x_m)\right| \le c_i, \tag{D.15}$$

for all  $i \in [m]$  and any points  $x_1, \ldots, x_m, x'_i \in \mathfrak{X}$ . Let f(S) denote  $f(X_1, \ldots, X_m)$ , then, for all  $\epsilon > 0$ , the following inequalities hold:

$$\mathbb{P}[f(S) - \mathbb{E}[f(S)] \ge \epsilon] \le \exp\left(\frac{-2\epsilon^2}{\sum_{i=1}^m c_i^2}\right) \tag{D.16}$$

$$\mathbb{P}[f(S) - \mathbb{E}[f(S)] \le -\epsilon] \le \exp\left(\frac{-2\epsilon^2}{\sum_{i=1}^m c_i^2}\right).$$
(D.17)

McDiarmid's inequality is used in several of the proofs in this book. It can be understood in terms of stability: if changing any of its argument affects f only in a limited way, then, its deviations from its mean can be exponentially bounded.

Εξαιτίας των δύο ανισοτήτων έχουμε το O(). Βλέμε θεώρημα 3.3 σε Mohri.

If we have a function:

$$|f(x_1,\ldots,x_i,\ldots,x_m)-f(x_1,\ldots,x_i',\ldots,x_m)| \le c_i$$
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What function do we care about for Rademacher complexity? Let's define

$$\Phi(S) = \sup_{f} \left( \mathbb{E}[f] - \hat{\mathbb{E}}_{S}[f] \right) = \sup_{f} \left( \mathbb{E}[f] - \frac{1}{m} \sum_{i} f(z_{i}) \right)$$
(11)

#### Lemma

# Moving to Expectation With probability at least $1 - \delta$ , $\Phi(S) \leq \mathbb{E}_{s}[\Phi(S)] + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$

Since  $f(z_1) \in [0, 1]$ , changing any  $z_i$  to  $z'_i$  in the training set will change  $\frac{1}{m} \sum_i f(z_i)$  by at most  $\frac{1}{m}$ , so we can apply McDiarmid's inequality with  $\epsilon = \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$  and  $c_i = \frac{1}{m}$ .

$$\begin{split} \delta &\leq e_{XP}\left(\frac{-2e^{L}}{\frac{m}{2}}\left(\frac{1}{e^{L}}\right)^{2}\right) = e_{XP}\left(-2me^{2}\right)\\ \ell_{H}(\delta) &\leq -2me^{2}\\ -\ell_{H}(\delta) &\geq e^{2} \geq 2\left|\frac{\ell_{H}\left(\frac{1}{\delta}\right)}{2m}\right\rangle \neq \epsilon \end{split}$$

Define a ghost sample  $S' = (z'_1, ..., z'_m) \sim D$ . How much can two samples from the same distribution vary?

#### Lemma

**Two Different Samples** 

$$\mathbb{E}_{S}[\Phi(S)] = \mathbb{E}_{S}\left[\sup_{f} (\mathbb{E}[f] - \hat{\mathbb{E}}_{S}[f])\right]$$
(12)  
(13)

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$$= \mathbb{E}_{\mathcal{S}}\left[\sup_{f \in \mathcal{F}} \left(\mathbb{E}_{\mathcal{S}'}\left[\hat{\mathbb{E}}_{\mathcal{S}'}\left[f\right]\right] - \hat{\mathbb{E}}_{\mathcal{S}}\left[f\right]\right)\right]$$
(13)

(14)

The expectation is equal to the expectation of the empirical expectation of all sets  $S^\prime$ 

### Step 2: Comparing two different empirical expectations

Define a ghost sample  $S' = (z'_1, ..., z'_m) \sim D$ . How much can two samples from the same distribution vary?

Lemma

**Two Different Samples** 

$$\mathbb{E}_{\mathcal{S}}[\Phi(\mathcal{S})] = \mathbb{E}_{\mathcal{S}}\left[\sup_{f} (\mathbb{E}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f])\right]$$
(12)

$$= \mathbb{E}_{\mathcal{S}}\left[\sup_{f \in F} \left(\mathbb{E}_{\mathcal{S}'}\left[\hat{\mathbb{E}}_{\mathcal{S}'}\left[f\right]\right] - \hat{\mathbb{E}}_{\mathcal{S}}\left[f\right]\right)\right]$$
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(15)

S and  $S^\prime$  are distinct random variables, so we can move inside the expectation

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(13)

$$\leq \mathbb{E}_{\mathcal{S},\mathcal{S}'}\left[\sup_{f} \left(\hat{\mathbb{E}}_{\mathcal{S}'}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f]\right)\right]$$
(14)

The expectation of a max over some function is at least the max of that expectation over that function

From *S*, *S'* we'll create *T*, *T'* by swapping elements between *S* and *S'* with probability .5. This is still idependent, identically distributed (iid) from *D*. They have the same distribution:

$$\hat{\mathbb{E}}_{S'}[f] - \hat{\mathbb{E}}_{S}[f] \sim \hat{\mathbb{E}}_{T'}[f] - \hat{\mathbb{E}}_{T}[f]$$
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(15)

Let's introduce  $\sigma_i$ :

$$\hat{\mathbb{E}}_{T'}[f] - \hat{\mathbb{E}}_{T}[f] = \frac{1}{m} \begin{cases} f(z_i) - f(z'_i) \text{ with prob .5} \\ f(z'_i) - f(z_i) \text{ with prob .5} \end{cases}$$
(16)
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(16)
$$= \frac{1}{m} \sum_{i} \sigma_i (f(z'_i) - f(z_i))$$
(17)

$$\mathbb{E}_{S,S'}\left[\sup_{f\in F}\left(\hat{\mathbb{E}}_{S'}\left[f\right]-\hat{\mathbb{E}}_{S}\left[f\right]\right)\right]=\mathbb{E}_{S,S',\sigma}\left[\sup_{f\in F}\left(\sum_{i}\sigma_{i}(f(z'_{i})-f(z_{i}))\right)\right].$$

# Before, we had $\mathbb{E}_{S,S',\sigma} \left[ \sup_{f \in F} \sum_{i} \sigma_i (f(z'_i) - f(z_i)) \right]$

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$$\mathbb{E}_{S,S',\sigma} \left[ \sup_{f \in F} \sum_{i} \sigma_{i} (f(z'_{i}) - f(z_{i})) \right]$$
  

$$\leq \mathbb{E}_{S,S',\sigma} \left[ \sup_{f \in F} \sum_{i} \sigma_{i} f(z'_{i}) + \sup_{f \in F} \sum_{i} (-\sigma_{i}) f(z_{i}) \right]$$
(18)
(19)

Taking the sup jointly must be less than or equal the individual sup.

Before, we had 
$$\mathbb{E}_{S,S',\sigma}\left[\sup_{f\in F}\sum_i \sigma_i(f(z'_i) - f(z_i))\right]$$

$$\leq \mathbb{E}_{S,S',\sigma} \left[ \sup_{i \in F} \sum_{i} \sigma_{i} f(z_{i}') + \sup_{f \in F} \sum_{i} (-\sigma_{i}) f(z_{i}) \right]$$
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(19)  
(20)

Linearity

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$$\leq \mathbb{E}_{S,S',\sigma} \left[ \sup_{f \in F} \sum_{i} \sigma_{i} f(z_{i}') \right] + \mathbb{E}_{S,S',\sigma} \left[ \sup_{f \in F} \sum_{i} (-\sigma_{i}) f(z_{i}) \right]$$
(19)  
$$= \mathscr{R}_{m}(F) + \mathscr{R}_{m}(F)$$
(20)

Definition

$$\Phi(S) \leq \mathbb{E}_{S}[\Phi(S)] + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$

Step 1

(21)

$$\sup_{f} \left( \mathbb{E}\left[f\right] - \hat{\mathbb{E}}_{\mathcal{S}}\left[f\right] \right) \le \mathbb{E}_{\mathcal{S}}\left[\Phi(\mathcal{S})\right] + \sqrt{\frac{\ln\frac{1}{\delta}}{2m}}$$
(21)

Definition of  $\boldsymbol{\Phi}$ 

$$\mathbb{E}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f] \leq \mathbb{E}_{\mathcal{S}}[\Phi(\mathcal{S})] + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$

(21)

Drop the sup, still true

$$\mathbb{E}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f] \le \mathbb{E}_{\mathcal{S},\mathcal{S}'}\left[\sup_{f} (\hat{\mathbb{E}}_{\mathcal{S}'}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f])\right] + \sqrt{\frac{\ln\frac{1}{\delta}}{2m}}$$
(21)  
Step 2

$$\mathbb{E}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f] \le \mathbb{E}_{\mathcal{S},\mathcal{S}',\sigma} \left[ \sup_{f \in F} \left( \sum_{i} \sigma_{i}(f(z_{i}') - f(z_{i})) \right) \right] + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$
(21)  
Step 3

$$\mathbb{E}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f] \leq 2\Re_m(F) + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$
(21)
Step 4

$$\mathbb{E}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f] \le 2\mathscr{R}_m(F) + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$
(21)

Recall that  $\hat{\mathscr{R}}_{\mathcal{S}}(F) \equiv \mathbb{E}_{\sigma} \left[ \sup_{f} \frac{1}{m} \sum_{i} \sigma_{i} f(z_{i}) \right]$ , so we apply McDiarmid's inequality again (because  $f \in [0, 1]$ ):

$$\mathscr{R}_{m}(F) \leq \hat{\mathscr{R}}_{S}(F) + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$
(22)

Putting the Pieces Together

With probability  $\geq 1 - \delta$ :

$$\mathbb{E}[f] - \hat{\mathbb{E}}_{\mathcal{S}}[f] \le \frac{2\mathscr{R}_m(F)}{2m} + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$
(21)

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$$\mathscr{R}_{m}(F) \leq \hat{\mathscr{R}}_{S}(F) + \sqrt{\frac{\ln \frac{1}{\delta}}{2m}}$$
(22)

Putting the two together:

$$\mathbb{E}[f] \leq \hat{\mathbb{E}}_{s}[f] + 2\mathcal{R}_{s}(F) + \mathcal{O}\left(\sqrt{\frac{\ln \frac{1}{\delta}}{m}}\right)$$

(23)

What about hypothesis classes?

t

Define:

$$Z \equiv X \times \{-1, +1\}$$
(24)  
$$F_h(x, y) \equiv \mathbb{1} [h(x) \neq y]$$
(25)  
$$F_H \equiv \{f_h : h \in H\}$$
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What about hypothesis classes?

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$$f_h(x,y) \equiv \mathbb{1}[h(x) \neq y]$$
(25)

$$F_H \equiv \{f_h : h \in H\}$$
(26)

We can use this to create expressions for generalization and empirical error:

$$R(h) = \mathbb{E}_{(x,y)\sim D} \left[ \mathbb{1} \left[ h(x) \neq y \right] \right] = \mathbb{E} \left[ f_h \right]$$
(27)

$$\hat{R}(h) = \frac{1}{m} \sum_{i} \mathbb{1} \left[ h(x_i) \neq y \right] = \hat{\mathbb{E}}_{\mathcal{S}} \left[ f_h \right]$$
(28)

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$$F_H \equiv \{f_h : h \in H\}$$
(26)

We can use this to create expressions for generalization and empirical error:

$$R(h) = \mathbb{E}_{(x,y)\sim D}[\mathbb{1}[h(x)\neq y]] = \mathbb{E}[f_h]$$
(27)

$$\hat{R}(h) = \frac{1}{m} \sum_{i} \mathbb{1} \left[ h(x_i) \neq y \right] = \hat{\mathbb{E}}_{\mathcal{S}} \left[ f_h \right]$$
(28)

We can plug this into our theorem!

## **Generalization bounds**

We started with expectations

$$\mathbb{E}[f] \le \hat{\mathbb{E}}_{\mathcal{S}}[f] + 2\hat{\mathscr{R}}_{\mathcal{S}}(F) + \mathcal{O}\left(\sqrt{\frac{\ln\frac{1}{\delta}}{m}}\right)$$
(29)

• We also had our definition of the generalization and empirical error:

$$R(h) = \mathbb{E}_{(x,y)\sim D}[\mathbb{1}[h(x)\neq y]] = \mathbb{E}[f_h] \quad \hat{R}(h) = \frac{1}{m}\sum_i \mathbb{1}[h(x_i)\neq y] = \hat{\mathbb{E}}_{\mathcal{S}}[f_h]$$

#### Generalization bounds

$$\hat{\mathscr{R}}_{S}(F_{H}) = \frac{1}{2}\hat{\mathscr{R}}_{S}(H)$$
(30)

$$\widehat{\mathfrak{R}}_{S}(\mathfrak{G}) = \frac{1}{2} \widehat{\mathfrak{R}}_{S_{\mathfrak{X}}}(\mathfrak{H}). \tag{3.16}$$

**Proof:** For any sample  $S = ((x_1, y_1), \ldots, (x_m, y_m))$  of elements in  $\mathfrak{X} \times \{-1, +1\}$ , by definition, the empirical Rademacher complexity of  $\mathcal{G}$  can be written as:

$$\begin{aligned} \widehat{\Re}_{S}(\mathfrak{G}) &= \mathbb{E}\left[\sup_{h\in\mathfrak{H}}\frac{1}{m}\sum_{i=1}^{m}\sigma_{i}\mathbf{1}_{h(x_{i})\neq y_{i}}\right] \\ &= \mathbb{E}\left[\sup_{h\in\mathfrak{H}}\frac{1}{m}\sum_{i=1}^{m}\sigma_{i}\frac{1-y_{i}h(x_{i})}{2}\right] \\ &= \frac{1}{2}\mathbb{E}\left[\sup_{h\in\mathfrak{H}}\frac{1}{m}\sum_{i=1}^{m}-\sigma_{i}y_{i}h(x_{i})\right] \\ &= \frac{1}{2}\mathbb{E}\left[\sup_{h\in\mathfrak{H}}\frac{1}{m}\sum_{i=1}^{m}\sigma_{i}h(x_{i})\right] = \frac{1}{2}\widehat{\Re}_{S_{\mathfrak{X}}}(\mathfrak{H}) \end{aligned}$$

where we used the fact that  $1_{h(x_i) \neq y_i} = (1 - y_i h(x_i))/2$  and the fact that for a fixed  $y_i \in \{-1, +1\}, \sigma_i$  and  $-y_i \sigma_i$  are distributed in the same way.

## **Generalization bounds**

We started with expectations

$$\mathbb{E}[f] \le \hat{\mathbb{E}}_{\mathcal{S}}[f] + 2\hat{\mathscr{R}}_{\mathcal{S}}(F) + \mathcal{O}\left(\sqrt{\frac{\ln\frac{1}{\delta}}{m}}\right)$$
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• We also had our definition of the generalization and empirical error:

$$R(h) = \mathbb{E}_{(x,y)\sim D}[\mathbb{1}[h(x)\neq y]] = \mathbb{E}[f_h] \quad \hat{R}(h) = \frac{1}{m}\sum_i \mathbb{1}[h(x_i)\neq y] = \hat{\mathbb{E}}_{\mathcal{S}}[f_h]$$

Combined with the previous result:

$$\hat{\mathscr{R}}_{\mathcal{S}}(F_{\mathcal{H}}) = \frac{1}{2}\hat{\mathscr{R}}_{\mathcal{S}}(\mathcal{H})$$
(30)

All together:

$$R(h) \le \hat{R}(h) + \hat{\mathscr{R}}_{S}(H) + \mathscr{O}\left(\sqrt{\frac{\log \frac{1}{\delta}}{m}}\right)$$
(31)

- Interaction of data, complexity, and accuracy
- Still very theoretical
- Next up: How to evaluate generalizability of specific hypothesis classes

Rademacher complexity provides nice guarantees

$$R(h) \leq \hat{R}(h) + \hat{\mathscr{R}}_{S}(H) + \mathscr{O}\left(\sqrt{\frac{\log \frac{1}{\delta}}{2m}}\right)$$

(32)

- But in practice hard to compute for real hypothesis classes
- Is there a relationship with simpler combinatorial measures?

Define the **growth function**  $\Pi_H : \mathbb{N} \to \mathbb{N}$  for a hypothesis set *H* as:

$$\forall m \in \mathbb{N}, \Pi_H(m) \equiv \max_{\{x_1, \dots, x_m\} \in X} \left| \{ (h(x_1), \dots, h(x_m) : h \in H \} \right|$$
(33)

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(33)

i.e., the number of ways *m* points can be classified using *H*.

If G is a function taking values in  $\{-1, +1\}$ , then

$$\mathscr{R}_m(G) \le \sqrt{\frac{2\ln\Pi_G(m)}{m}} \tag{34}$$

# Uses Masart's lemma (Theorem 3.7)

**Corollary 3.9 (Growth function generalization bound)** Let  $\mathfrak{H}$  be a family of functions taking values in  $\{-1, +1\}$ . Then, for any  $\delta > 0$ , with probability at least  $1 - \delta$ , for any  $h \in \mathfrak{H}$ ,

$$R(h) \le \widehat{R}_S(h) + \sqrt{\frac{2\log \Pi_{\mathcal{H}}(m)}{m}} + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$
(3.22)

Not very convenient since it requires computing  $\Pi_H(m)$ ,  $\forall m$ 

# Vapnik-Chervonenkis Dimension





$$VC(H) \equiv \max\left\{m : \Pi_H(m) = 2^m\right\}$$
(35)

## Vapnik-Chervonenkis Dimension





$$VC(H) \equiv \max\left\{m \colon \Pi_H(m) = 2^m\right\}$$
(35)

The size of the largest set that can be fully shattered ( $\theta \rho \nu \mu \mu \alpha \tau i \sigma \tau \epsilon i$ ) by *H*.

Entropy Properties of a Decision Rule Class with ML abilities - Alexey Chervonenkis lecture

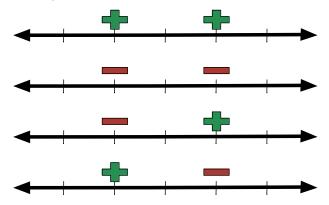
- Need upper and lower bounds
- Lower bound: example
- Upper bound: Prove that no set of d + 1 points can be shattered by H (harder)

• What about two points?

### Intervals

What is the VC dimension of [a, b] intervals on the real line.

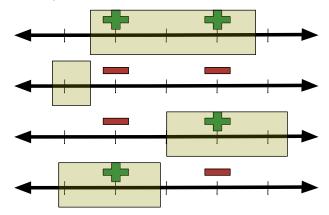
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## Intervals

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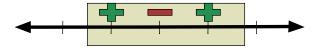
• What about two points?



• Two points can be perfectly classified, so VC dimension  $\geq 2$ 

- Two points can be perfectly classified, so VC dimension  $\geq$  2
- What about three points?

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- Two points can be perfectly classified, so VC dimension  $\geq$  2
- What about three points?
- No set of three points can be shattered
- Thus, VC dimension of intervals is 2

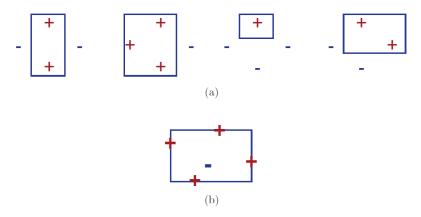
## Hyperplanes



#### Figure 3.2

Unrealizable dichotomies for four points using hyperplanes in  $\mathbb{R}^2$ . (a) All four points lie on the convex hull. (b) Three points lie on the convex hull while the remaining point is interior.

# Axis-aligned-rectangles



#### Figure 3.3

VC-dimension of axis-aligned rectangles. (a) Examples of realizable dichotomies for four points in a diamond pattern. (b) No sample of five points can be realized if the interior point and the remaining points have opposite labels.

$$\{t \to \sin(\omega x) : \omega \in \mathbb{R}\}$$
(36)

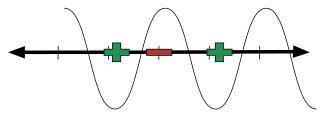
Can you shatter three points?

# **Sine Functions**

 Consider hypothesis that classifies points on a line as either being above or below a sine wave

$$\{t \to \sin(\omega x) : \omega \in \mathbb{R}\}$$
(36)

Can you shatter three points?



$$\{t \to \sin(\omega x) : \omega \in \mathbb{R}\}$$
(36)

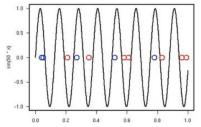
• Can you shatter four points?

$$\{t \to \sin(\omega x) : \omega \in \mathbb{R}\}$$
(36)

• How many points can you shatter?

$$\{t \to \sin(\omega x) : \omega \in \mathbb{R}\}\tag{36}$$

- Thus, VC dim of sine on line is  $\infty$ 



VC dimension obviously encodes the complexity of a hypothesis class, but we want to connect that to Rademacher complexity and the growth function so we can prove generalization bounds. VC dimension obviously encodes the complexity of a hypothesis class, but we want to connect that to Rademacher complexity and the growth function so we can prove generalization bounds.

# Theorem

**Sauer's Lemma** Let *H* be a hypothesis set with VC dimension *d*. Then  $\forall m \in \mathbb{N}$ 

$$\Pi_{H}(m) \leq \sum_{i=0}^{d} \binom{m}{i} \equiv \Phi_{d}(m)$$
(37)

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### Theorem

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(37)

This is good because the sum when multiplied out becomes  $\binom{m}{i} = \frac{m \cdot (m-1) \dots}{i!} = \mathcal{O}(m^d)$ . When we plug this into the learning error limits:  $\log(\Pi_H(2m)) = \log(\mathcal{O}(m^d)) = \mathcal{O}(d \log m)$ .

# Sauer's Lemma

Definition. Growth Function:

$$\Pi_F(n) = \max\{|F_{|s} : s \subseteq \mathcal{X}, |s| = n\}$$

**Definition.** VC dimension

$$d_{\rm VC}(F) = \max\{|s|: s \subseteq \mathcal{X}, f \text{ shatters } s\}$$

Here, we say that a family of binary functions F shatters a set  $S \in \mathcal{X}$  if  $F_{|S} = 2^{|S|}$ .

**Theorem 2.1.** Sauer's Lemma: If  $F \subseteq \{\pm 1\}^{\mathcal{X}}$  and  $d_{VC} = d$ , then  $\Pi_F(n) \leq \sum_{i=0}^d {n \choose i}$ . And for  $n \geq d$ ,  $\Pi_F(n) \leq \left(\frac{en}{d}\right)^d$ 

That means: if  $d_{VC}(F)$  is  $\infty$ , we always get exponential growth function; however, if  $d_{VC}(F) = d$  is finite, the growth function increases exponentially up to d and polynomially for n > d.

PROOF. Fix  $(x_1, \ldots, x_n) \in \mathcal{X}$ , and consider a table containing the values of functions in the class  $F_{|x_1^n}$  restricted to the sample. For instance, consider the following example:

	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$
$f_1$	-	+	-	+	+
$f_2$	+	-	-	+	+
$f_3$	+	+	+	-	+
$f_4$	-	+	+	-	-
$f_5$	-	-	-	+	-

Each row is one possible evaluation of the functions in F on the fixed sample, and the cardinality of  $F_{|x_1^n}$  equals to the number of rows. We transform the table by "shifting" columns.

**Definition.** shifting column i: for each row, replace a "+" in column i with a "-" unless it would produce a row that is already in the table.

After applying the shifting operation in order from  $x_1$  to  $x_5$ , we get the table  $(F_{|x_1^n}^*)$ :

	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$
$f_1$	-	+	-	-	-
$f_2$	-	-	-	+	+
$f_3$	-	-	-	-	+
$f_4$	-	-	-	-	-
$f_5$	-	-	-	+	-

#### **Observations:**

- (1) Size of the table unchanged, because the rows in  $F_{|x_1^n|}^*$  are still distinct;
- (2) The table  $F_{|x_1^n|}^*$  exhibits "closed below" property, i.e., for each row containing a "+", replacing that "+" with a "-" produces another row in the table.
- (3)  $d_{VC}(F_{|x_1^n}^*) \leq d_{VC}(F_{|x_1^n})$ . To see this, consider the application of the shifting operation to a single column, and notice that if  $F^*$  (after shifting) shatters a subset of columns, then so does F (before shifting).

# Therefore,

- (3) and (2)  $\Rightarrow F^*$  can not have more than d "+"'s in a row. Hence, #row of  $F^* \leq \sum_{i=0}^d {n \choose i}$ ;
- $(1) \Rightarrow |F_{|x_1^n|} \le \sum_{i=1}^d \binom{n}{i}$

Is this combinatorial expression really  $\mathcal{O}(m^d)$ ?

$$\begin{split} \sum_{i=0}^{d} \binom{m}{i} &\leq \sum_{i=0}^{d} \binom{m}{i} \left(\frac{m}{d}\right)^{d-i} & \frac{m}{d} \geq 1 \\ &\leq \sum_{i=0}^{m} \binom{m}{i} \left(\frac{m}{d}\right)^{d-i} & \overline{u}_{\mathbb{P}} \circ \sigma \mathcal{V}_{\mathbb{D}} \circ \sigma \mathcal{$$

Combining our previous generalization results with Sauer's lemma, we have that for a hypothesis class *H* with VC dimension *d*, for any  $\delta > 0$  with probability at least  $1 - \delta$ , for any  $h \in H$ ,

$$R(h) \le \hat{R}(h) + \sqrt{\frac{2d\log\frac{em}{d}}{m}} + \sqrt{\frac{\log\frac{1}{\delta}}{2m}}$$
(43)

- Infinite hypothesis class is PAC-learnable iff it has finite VC dimension
- We're now going to see if we can find an algorithm that has good VC dimension
- And works well in practice ... Support Vector Machines